

Motivation

Nuclear Fusion offers the potential for limitless, clean energy. Inertial Confinement Fusion (ICF) achieves nuclear fusion by compressing a tiny fuel pellet to extreme temperatures and pressures using a precisely controlled laser pulse.

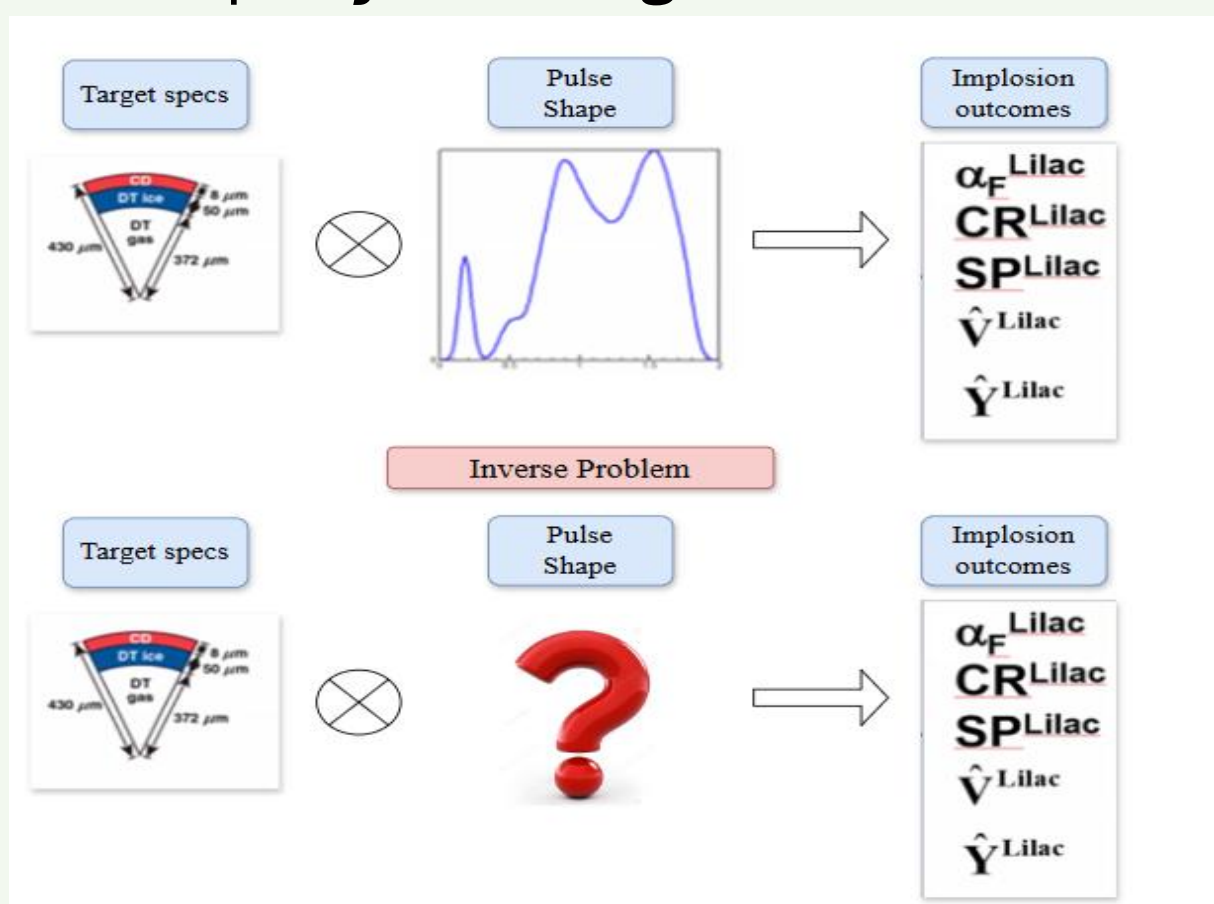
Challenges:

The right laser pulse shape is critical to achieve desired fusion outcomes.

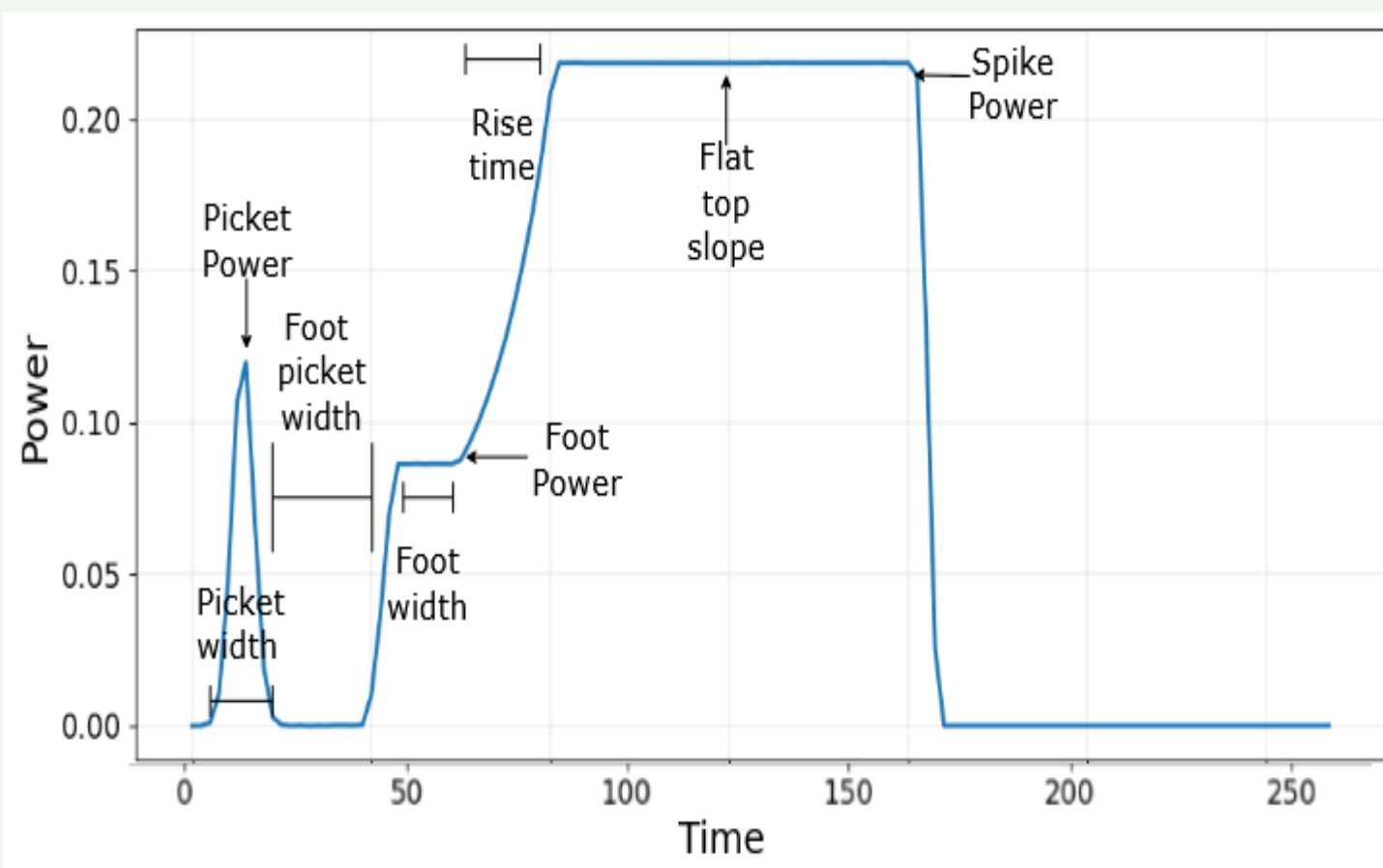
Designing it is currently a manual and cumbersome process

Goal:

Use generative modeling to get the desired pulse shape **by inverting the outcomes**



The Laser Pulse



Approach

Auto-regressive:

- We approach the pulse shape generation as an auto-regressive task where we “prompt” the model with the desired outcomes and the target specs.
- The pulse shape is generated auto-regressively using sequence generation model like a Transformer or LSTM

Generative modeling:

- The inverse problem can have multiple solutions since different pulse shapes can result in similar outcomes.
- However, some pulse shapes are more physically plausible than others and hence multiple options are desirable.
- We approach this as a generative modeling task where the model produces a distribution over pulse shapes

Experiments:

- We experiment with different model architectures and output probability distributions – both continuous and discrete.

Training Setup

Multi-objective loss:

- *Reconstruction error:* To ensure the model generates pulse shapes that are in-distribution

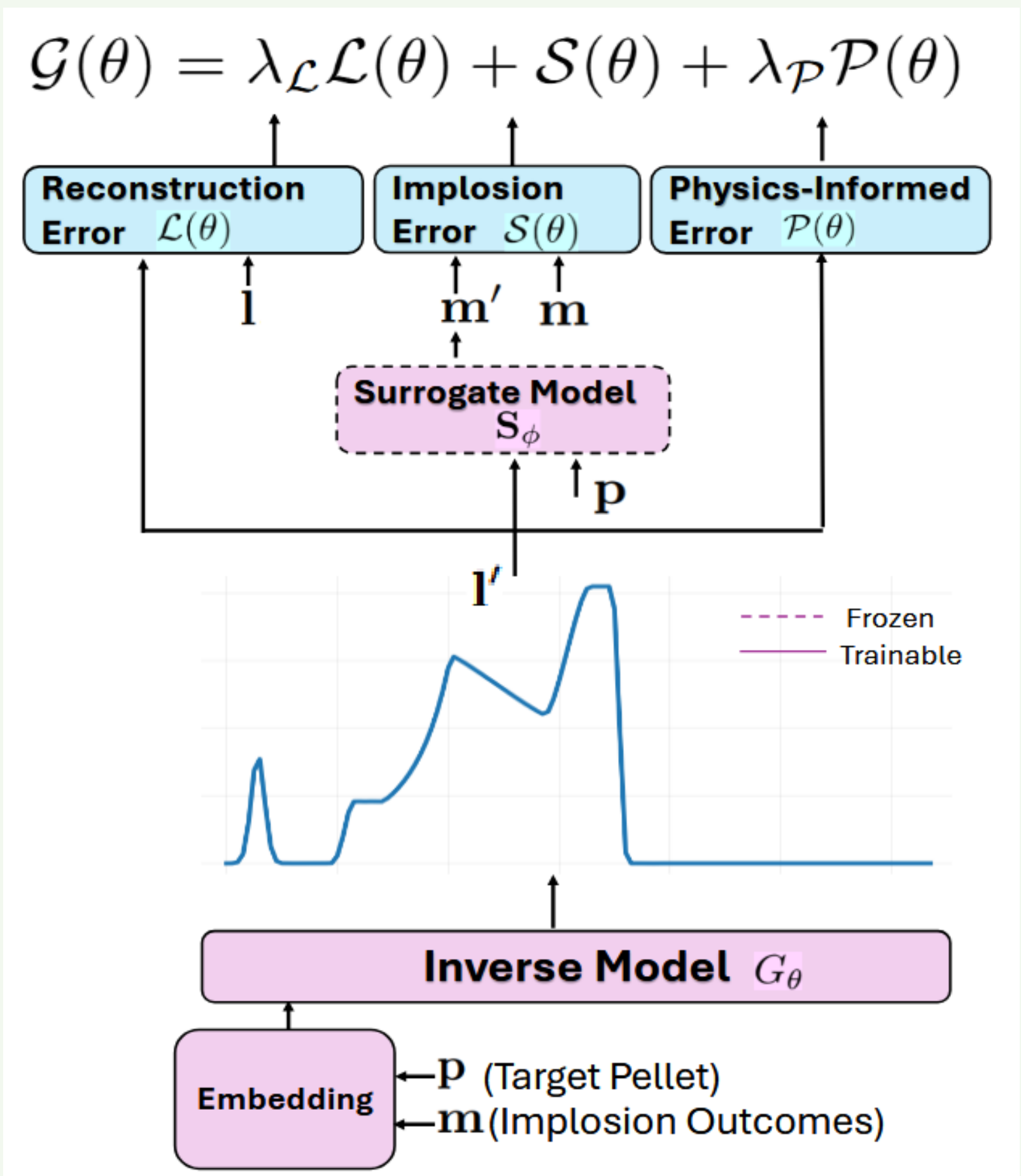
- *Implosion error:* To ensure the generated pulse shapes produce the desired fusion outcomes

- *Physics-informed error:* To ensure the generated pulse shaped adhere to physical constraints

The three terms are weighted according the priority

Surrogate model:

The generated pulse shapes are passed through a surrogate to test if they produce the desired outcomes



Results

Approach	Diversity ↑	m Error ↓	Reconstruction Error ↓	Energy Conservation ↓
LPDS _{LSTM}	–	1.65%	0.0001	0.66%
LPDS _{Transformer}	–	1.94%	0.0008	0.95%
LPDS _{GaussianAR}	0.42	1.89% ± 0.01	0.0005 ± 2e ⁻⁵	0.58% ± 0.004
LPDS _{MixtureOfGaussianAR}	0.56	1.95% ± 0.09	0.0006 ± 8e ⁻⁵	1.58% ± 0.006
LPDS _{CategoricalAR}	0.39	2.01% ± 0.04	0.0009 ± 5e ⁻⁵	1.18% ± 0.08
LPDS _{LSTM, w/o S}	–	3.9%	0.0004	0.69%
LPDS _{Transformer, w/o S}	–	4.4%	0.001	1.23%
LPDS _{LSTM, w/o P}	–	1.85%	0.0001	0.95%
LPDS _{Transformer, w/o P}	–	2.1%	0.0009	1.3%

Table 1: LPDS model performance. ± denotes standard deviation over seeds. For the predictive auto-regressive models (LPDS_{LSTM}, LPDS_{Transformer}), diversity is not defined since they are deterministic.

- Implosion loss is critical to reduce the implosion error
- LSTM gives the lowest reconstruction error and implosion error (m-error)

Example Pulse Shapes

Multiple samples generated by LSTM Gaussian model for 4 cases

