

Flood Prediction with Graph Neural Networks

Arnold Kazadi¹, James Doss-Gollin², Antonia Sebastian³, Arlei Silva¹

¹ Computer Science, Rice University

² Civil and Environmental Engineering, Rice University

³ Earth, Marine and Environmental Sciences, University of North Carolina at Chapel Hill

Introduction

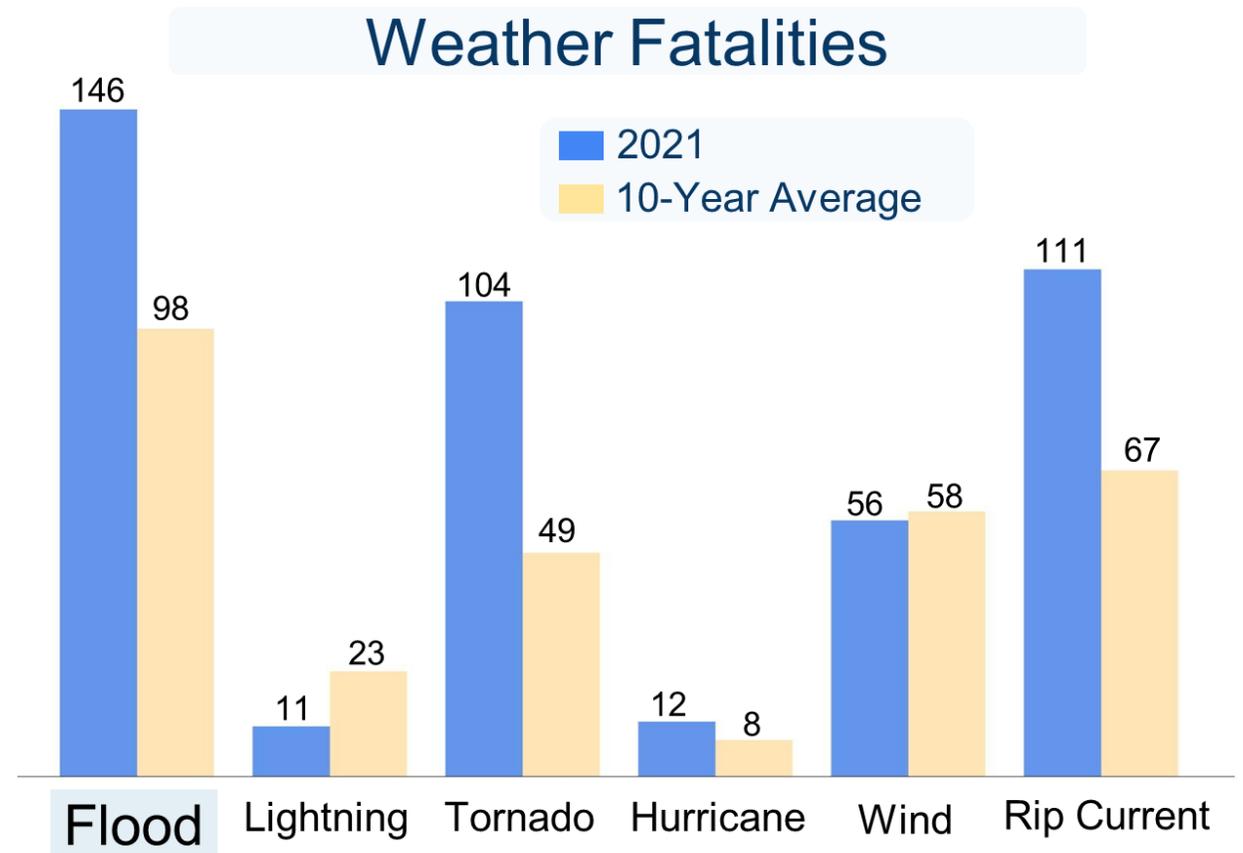
- Flooding: one of the most devastating hazards in the world.
- E.g., Hurricane Harvey's flooding led to **\$125 billion** in losses, **30,000+ people displaced**, and **200,000+ damaged homes and businesses**



Source: cnn.com

Introduction

- Flooding: one of the most devastating hazards in the world.
- Climate change \Rightarrow More precipitation \Rightarrow More flooding
- E.g., Hurricane Harvey's flooding led to **\$125 billion** in losses, **30,000+** people displaced, and **200,000+** damaged homes and businesses

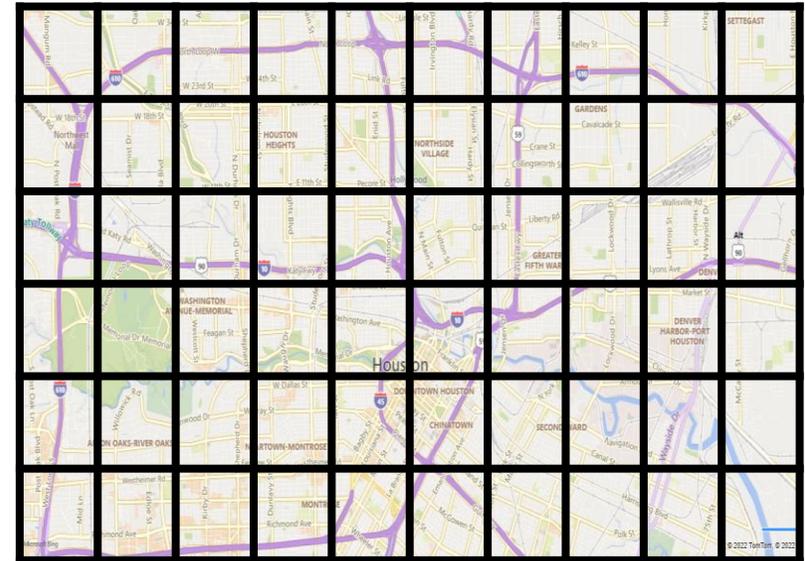
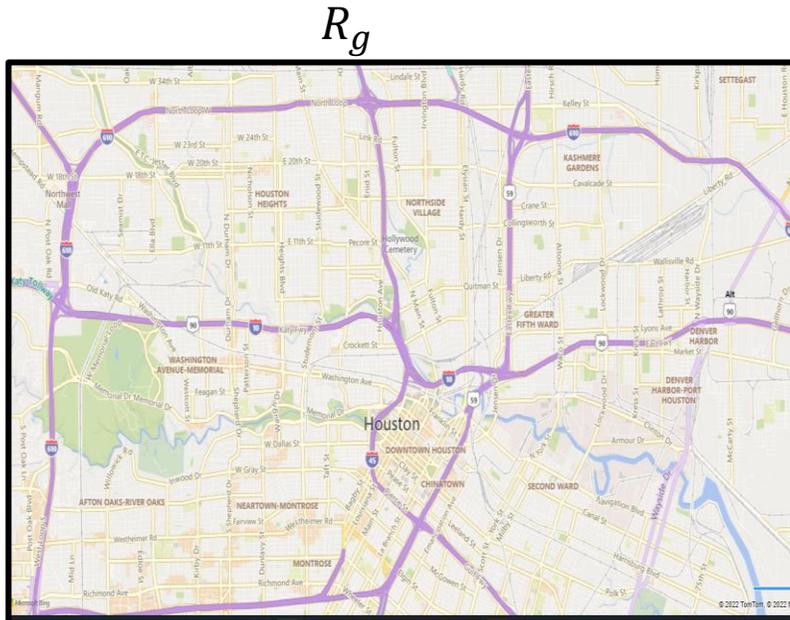


Introduction

- Popular approaches in practice simulate flooding by solving hydrodynamics (differential) equations (e.g., Saint-Venant equations)
 - Time consuming
 - Not scalable
- Our approach: FloodGNN flood prediction with graph neural networks.

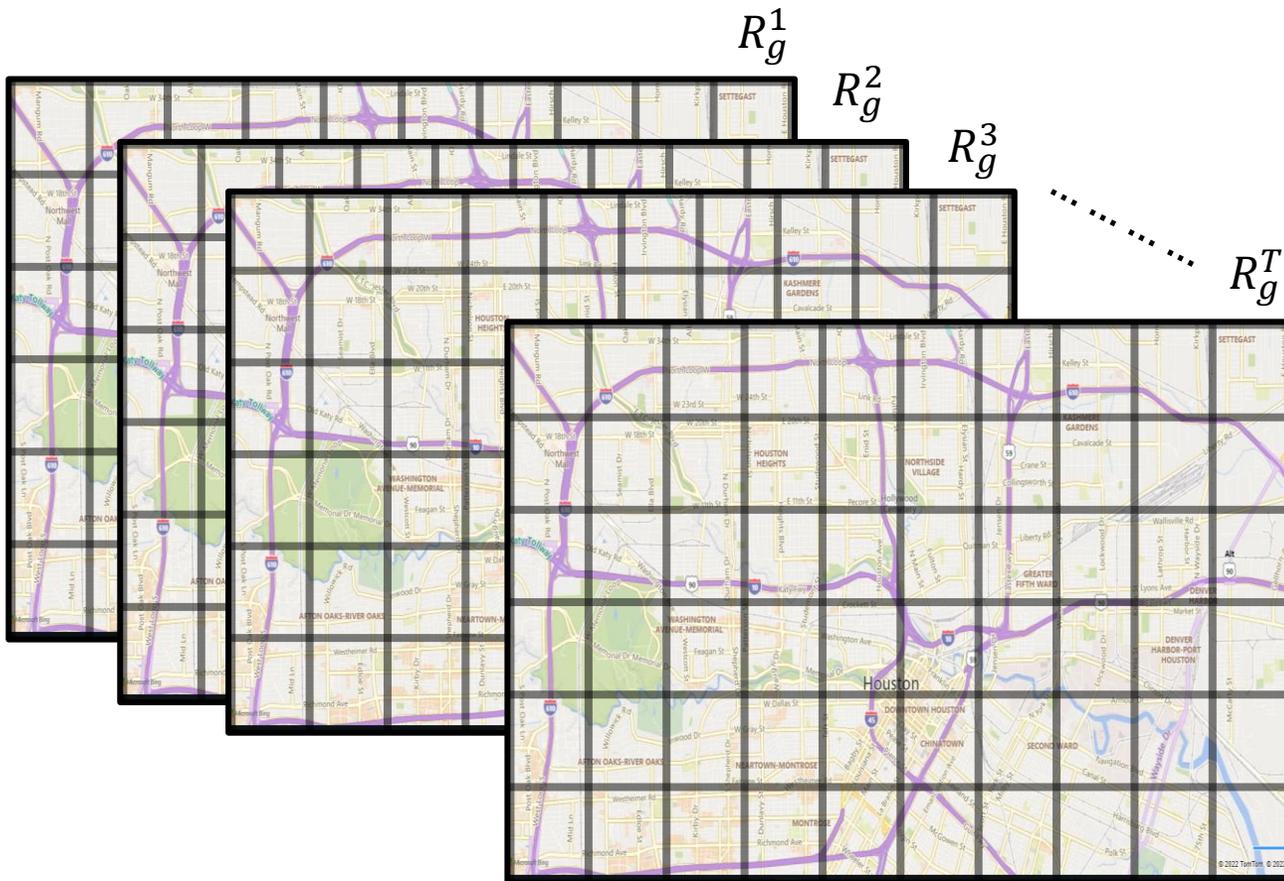
Proposed Method

- A region R_g is represented as a mesh.



Proposed Method

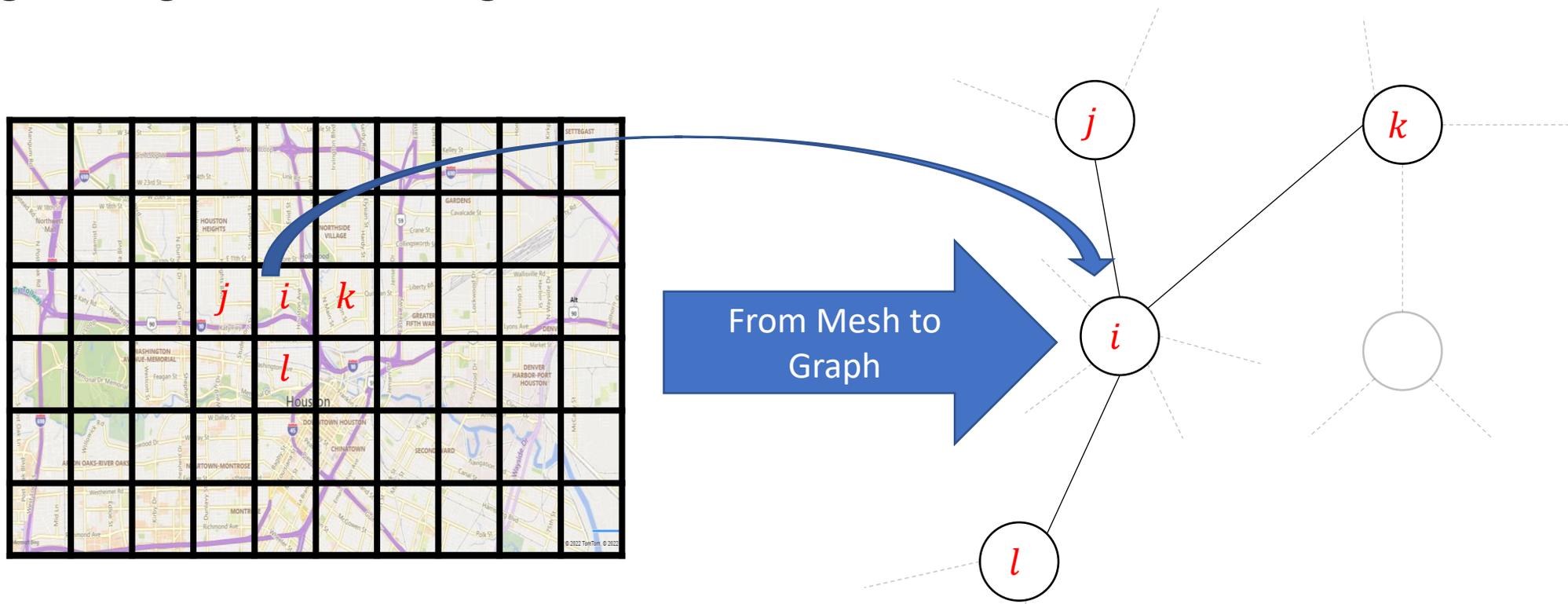
- Flooding events of a region R_g given as a time series $R_g^1, R_g^2, R_g^3 \dots, R_g^T$



Proposed Method

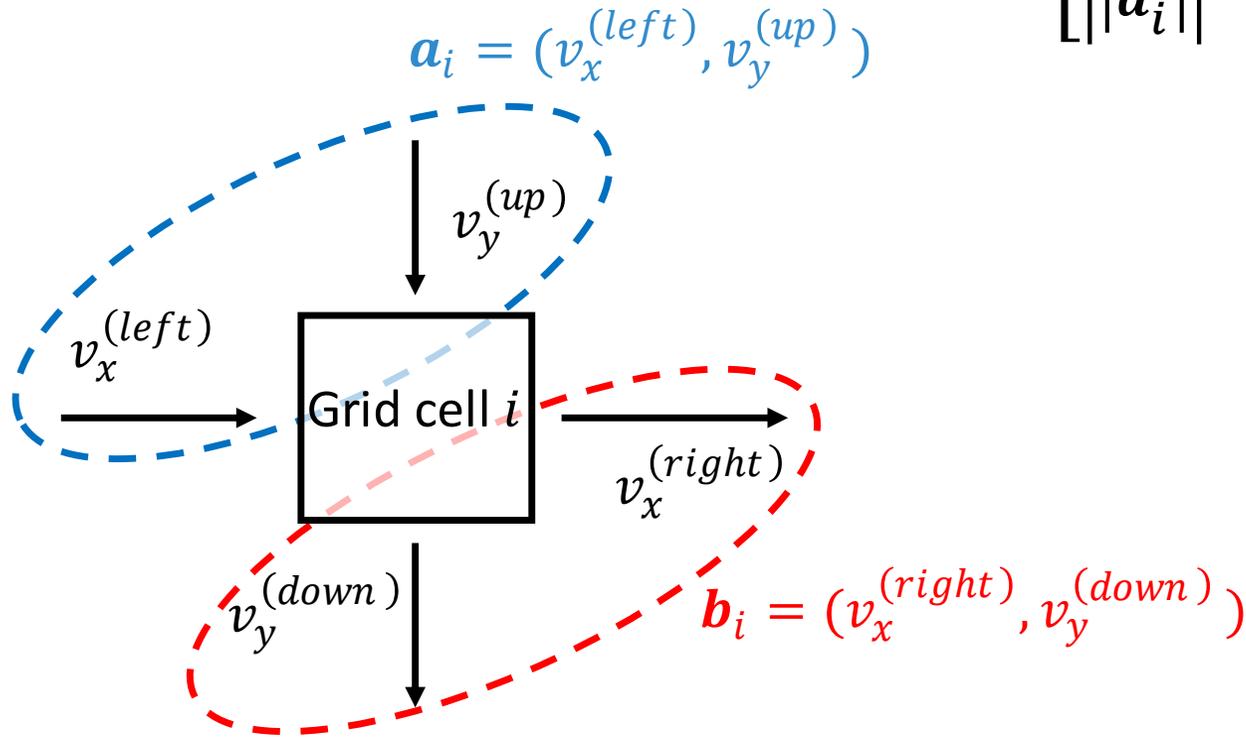
Graph representation from Mesh (GNN with mesh *).

- Cell $i \rightarrow$ node i
- Neighboring cells of $i \rightarrow$ edges



For each node i

- Vector features \mathbf{V}_i^t (velocities) = $\left[\frac{\mathbf{a}_i^t}{\|\mathbf{a}_i^t\|}, \frac{\mathbf{b}_i^t}{\|\mathbf{b}_i^t\|} \right]^T \in R^{2 \times 2}$

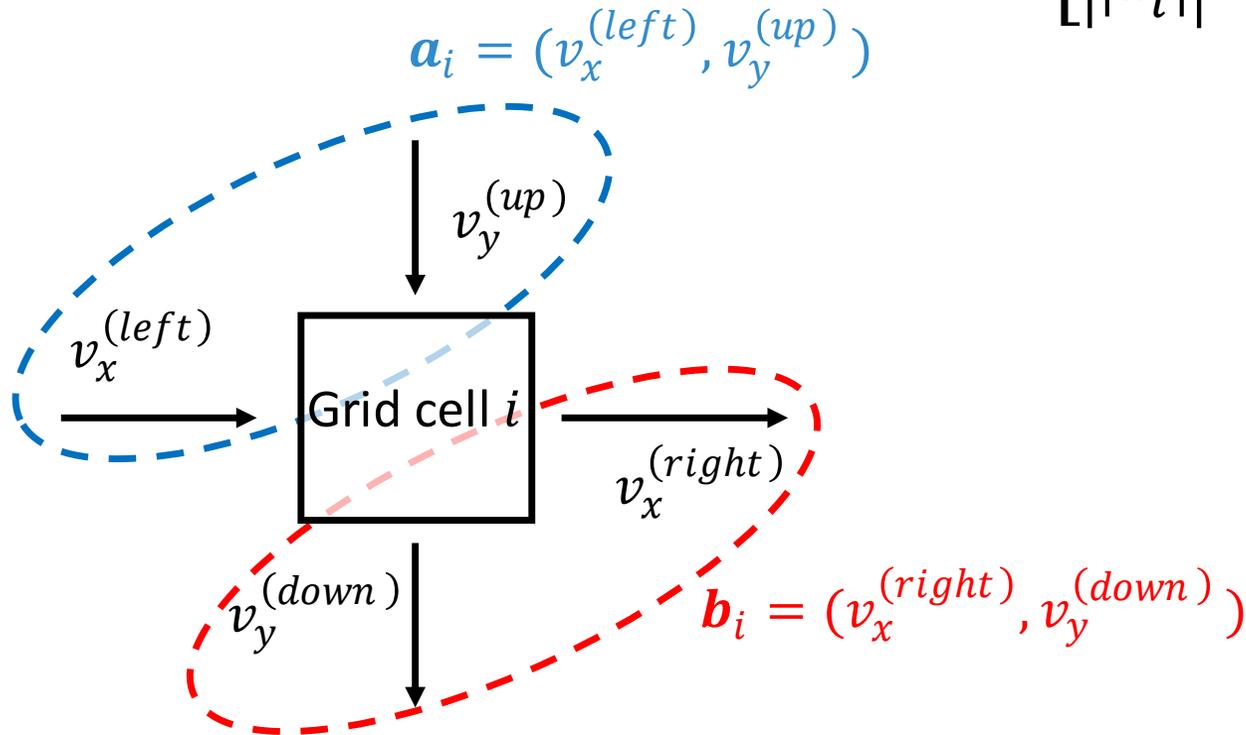


- Scalar feature \mathbf{s}_i^t

- e_i : ground elevation ; n_i : friction; d_i : distance to stream; w_i^t : water-depth

For each node i

- Vector features V_i^t (velocities) = $\left[\frac{a_i^t}{\|a_i^t\|}, \frac{b_i^t}{\|b_i^t\|} \right] \in R^{2 \times 2}$



Geometric vector perceptrons (GVP)*

$$(s', V') = GVP(s, V)$$

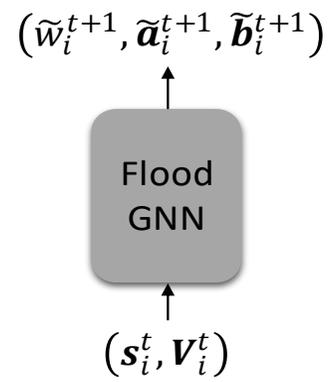
Where $s', s \in R^n$; $V', V \in R^{m \times p}$

* Bowen Jing, Stephan Eismann, Patricia Suriana, Raphael John Lamarre Townshend, and Ron Dror. *Learning from protein structure with geometric vector perceptrons*, ICLR 2021

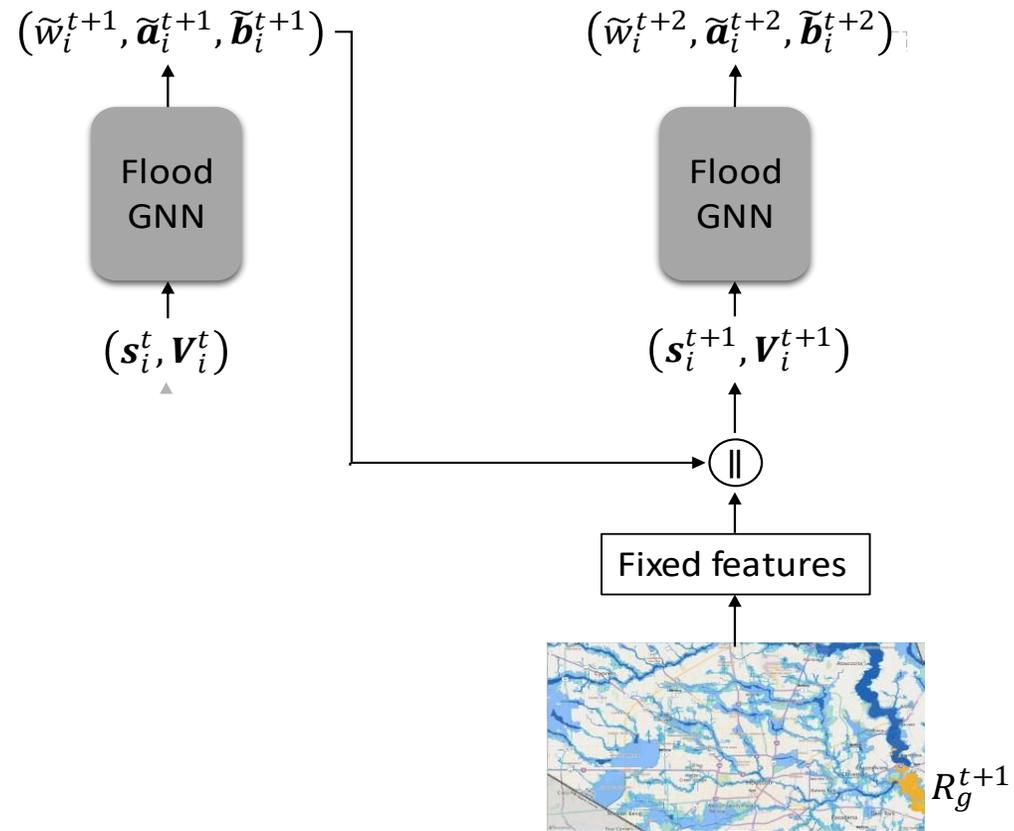
- Scalar feature s_i^t

- e_i : ground elevation ; n_i : friction; d_i : distance to stream; w_i^t : water-depth

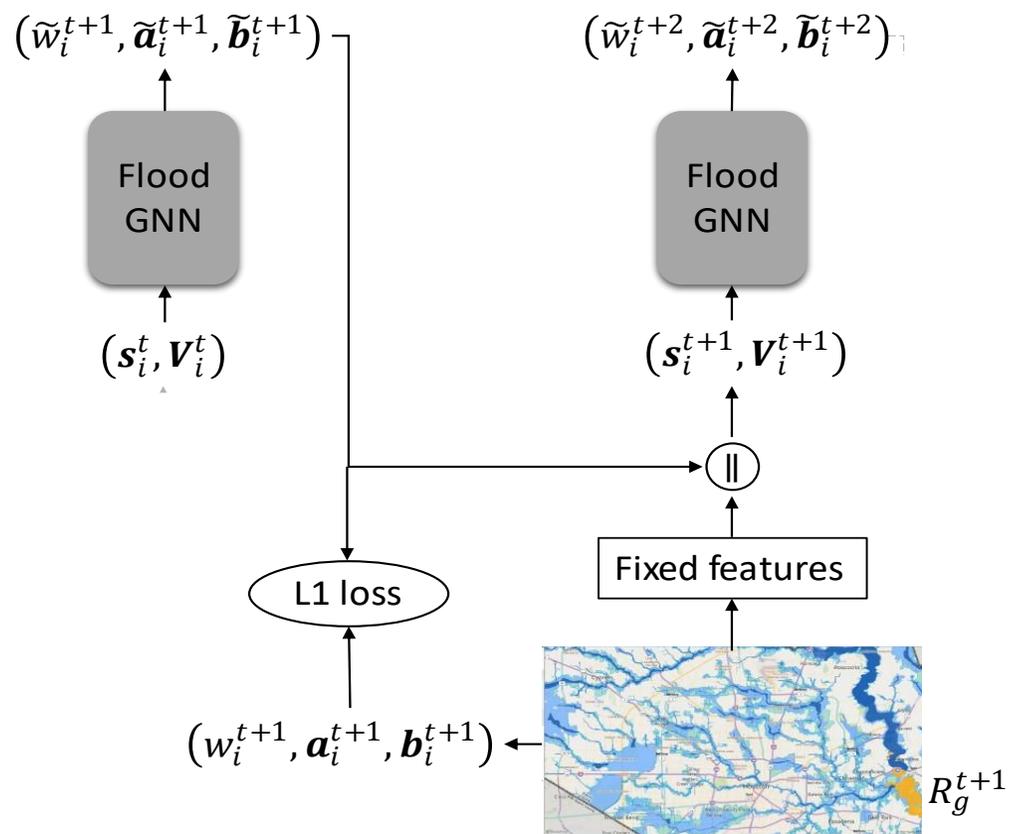
Proposed Method



Proposed Method



Proposed Method



Experiments

RMSE (lower better)					
time-step t	1	2	3	4	5
FloodRNN	.22 ± .030	.33 ± .030	.41 ± .031	.48 ± .034	.55 ± .038
FloodGNN-NoV	.25 ± .030	.40 ± .031	.51 ± .021	.60 ± .007	.66 ± .006
FloodGNN (Ours)	.17 ± .031	.27 ± .043	.34 ± .040	.39 ± .037	.44 ± .036
R^2 (higher better)					
time-step t	1	2	3	4	5
FloodRNN	.95 ± .0160	.87 ± .0390	.79 ± .0540	.72 ± .0620	.66 ± .0660
FloodGNN-NoV	.95 ± .0023	.88 ± .0069	.80 ± .0177	.71 ± .0356	.63 ± .0571
FloodGNN (Ours)	.98 ± .0028	.93 ± .0063	.89 ± .0083	.85 ± .0088	.80 ± .0091

- **FloodRNN**: RNN-based method
- **FloodGNN**: Our proposed method
- **FloodGNN-NoV**: FloodGNN variant, velocities as scalar features.

Experiments

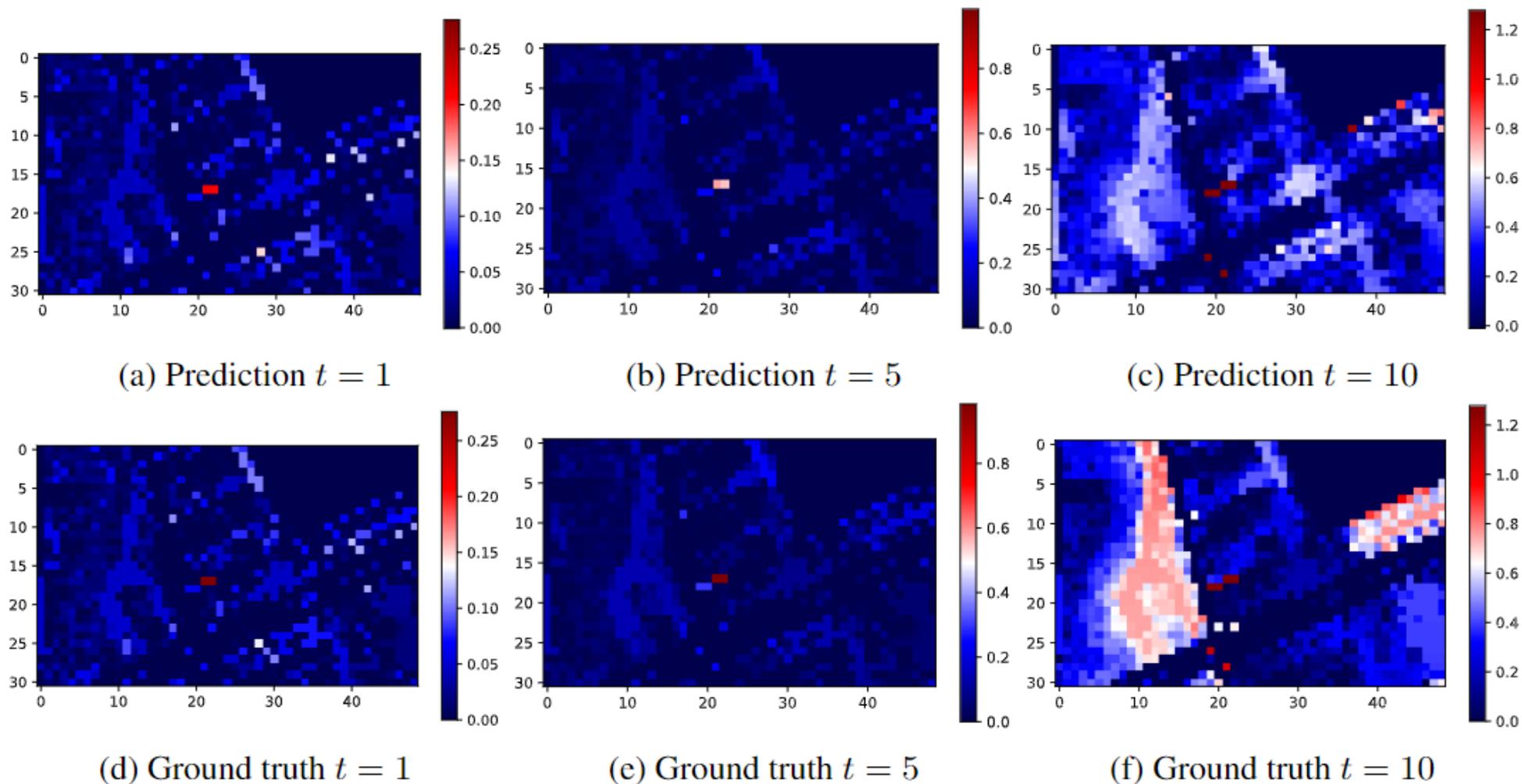


Figure 3: Comparison between real data (bottom row) and predictions from our model (top row).

Experiments

Predictions follow trend, even though with underestimation.

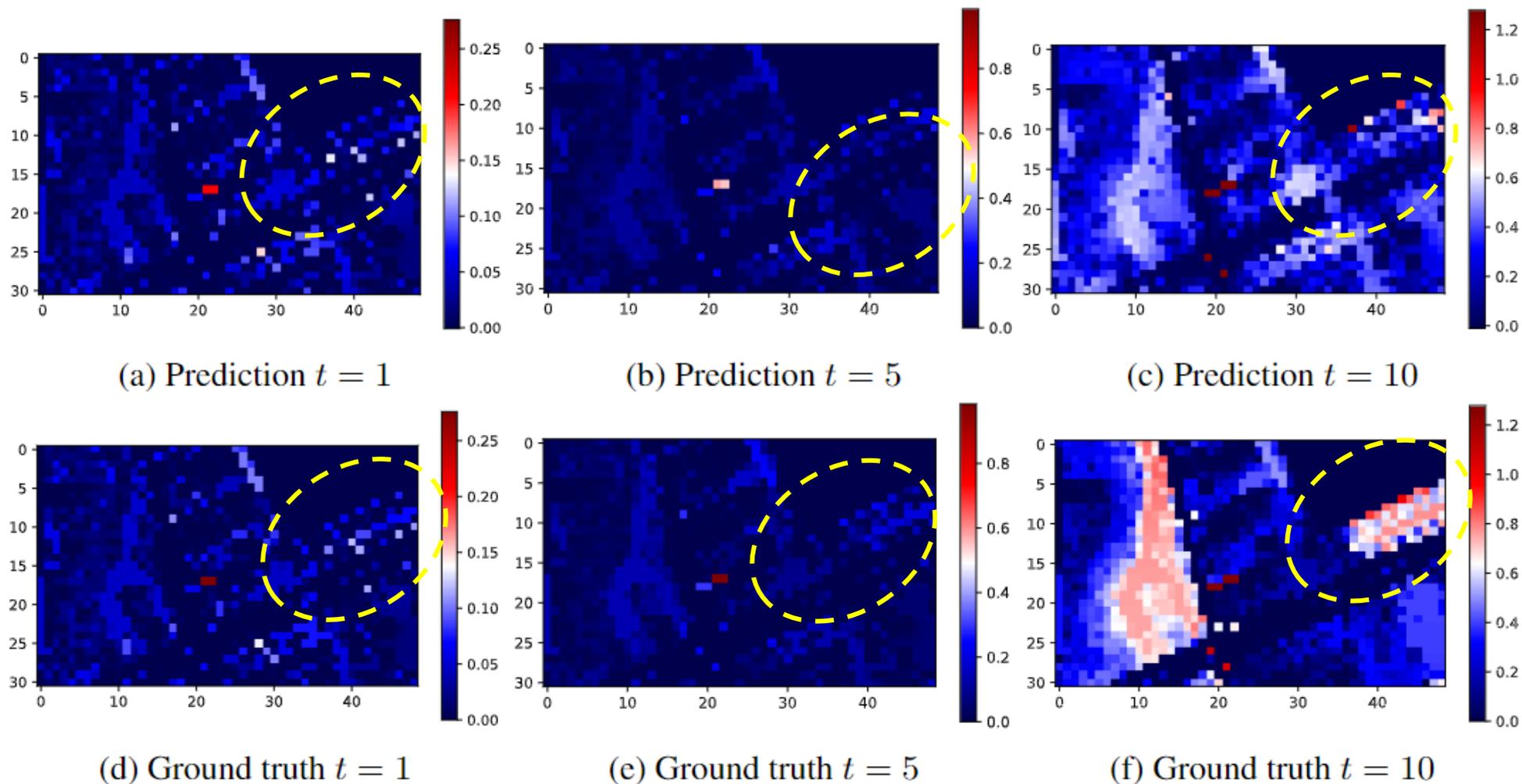


Figure 3: Comparison between real data (bottom row) and predictions from our model (top row).

Conclusion and ongoing work

- FloodGNN: spatio-temporal GNN for flood prediction.
- FloodGNN outperforms RNN-based model (no spatial relation).
- FloodGNN performs better with velocities as vector features.
- Future/ongoing work
 - Rainfall data input
 - Adaptive and irregular mesh representation
 - Physics-based constraints

For more information

- Email: akn7@rice.edu
- Website: <https://kantz76.github.io/>