

Short-term Prediction and Filtering of Solar Power using State-space Gaussian Processes

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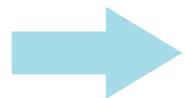
Why is solar power nowcasting important?

Nowcasting - Prediction in the very near future. Typically 2~6 hours ahead.

- Adoption of renewable energy sources have increased (which is good!)

However,

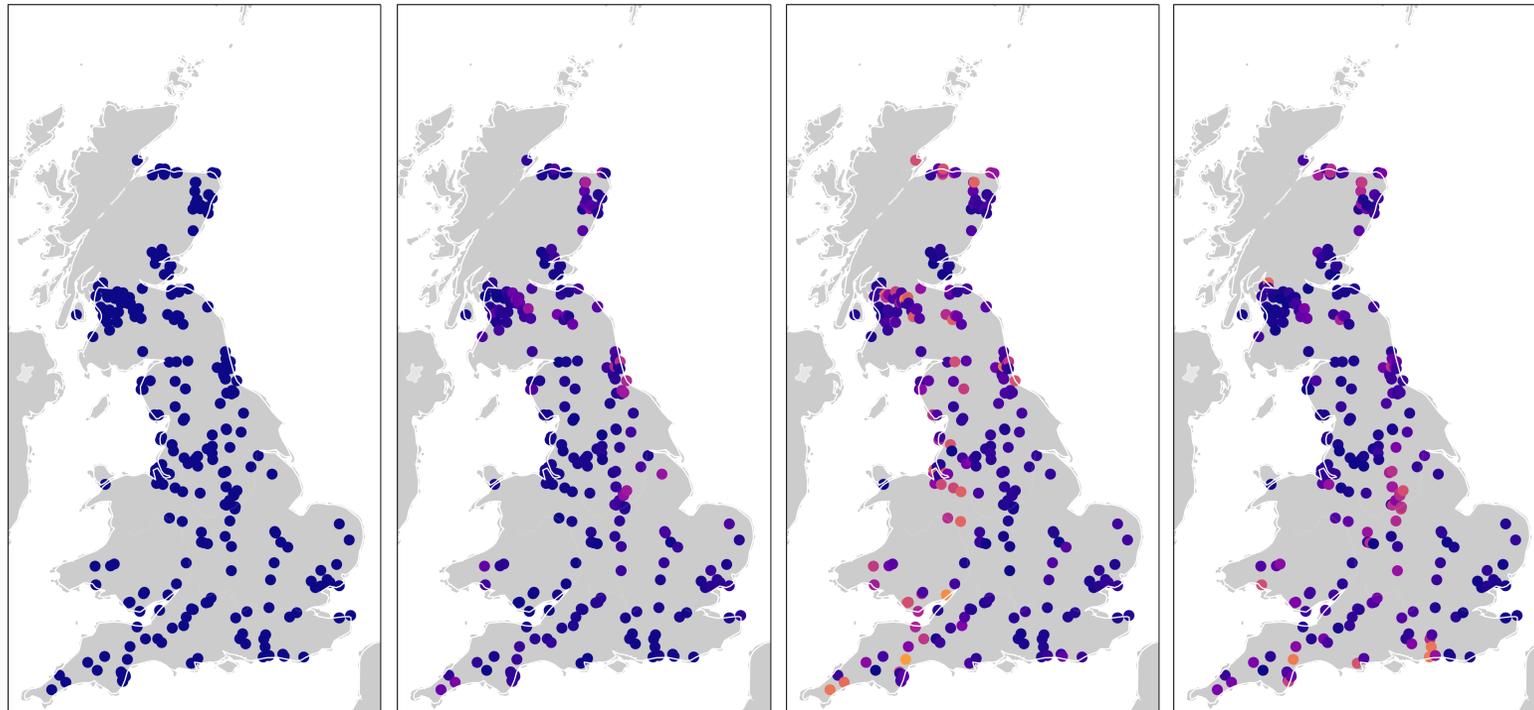
- Solar power is intermittent
- Back-up “spinning” reserves emit large amounts of CO₂ [1]



Crucial to increase accuracy of predictions with **uncertainties**

UK Photovoltaics (PV) dataset

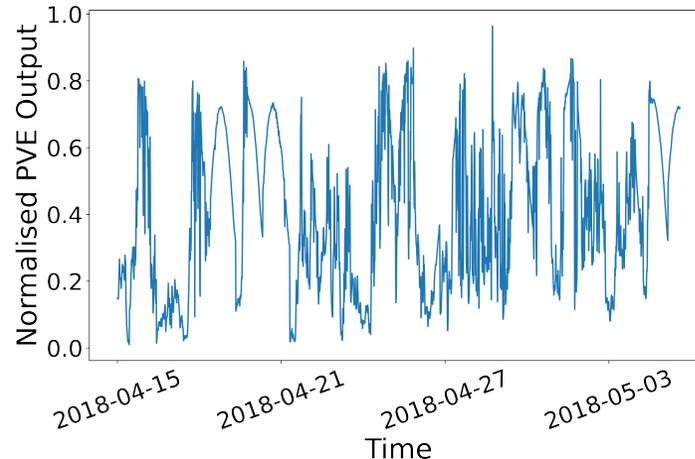
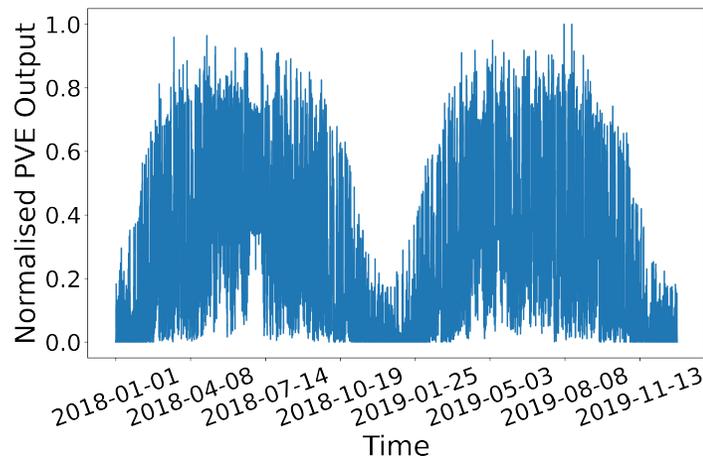
PVE at 2018-01-01 08:00:00 PVE at 2018-01-01 10:00:00 PVE at 2018-01-01 12:00:00 PVE at 2018-01-01 14:00:00



- Access to solar PV readings for 1311 stations across the UK*
- Select data to be between 08:00-16:00

*https://huggingface.co/datasets/openclimatefix/uk_pv

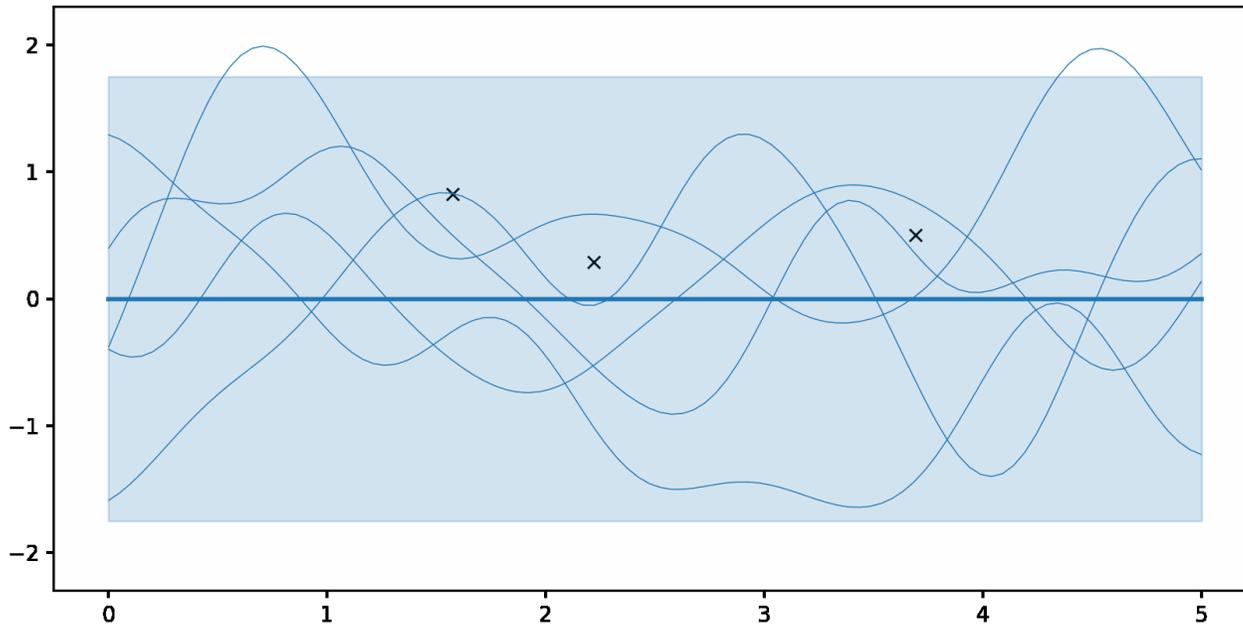
UK Photovoltaics (PV) dataset



PV timeseries at a single station (annual and daily scales)

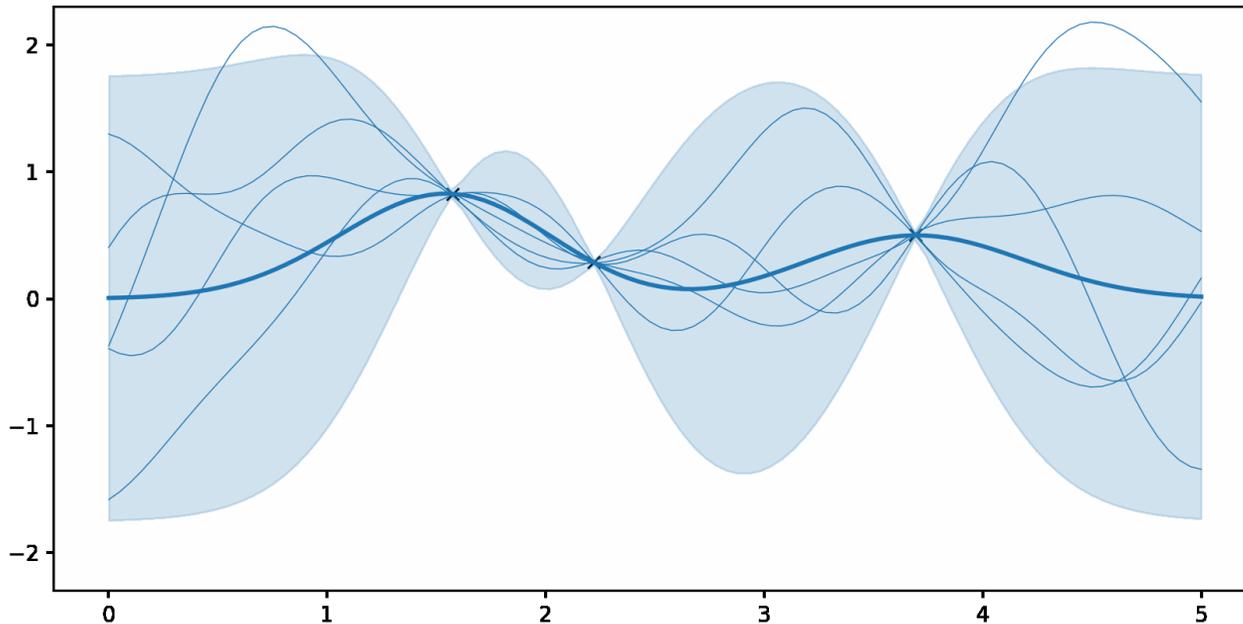
- Remove outliers and scale by total capacity
⇒ Data between 0 and 1
- Timeseries exhibits strong annual and daily seasonality
- $\mathcal{O}(10^5)$ data points

Gaussian Processes



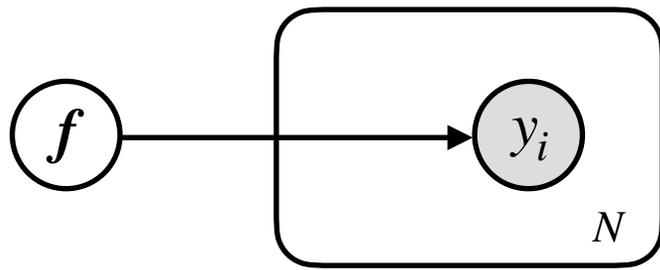
- GPs provide flexible priors for modelling data
- Can get predictions + uncertainty estimates

Gaussian Processes

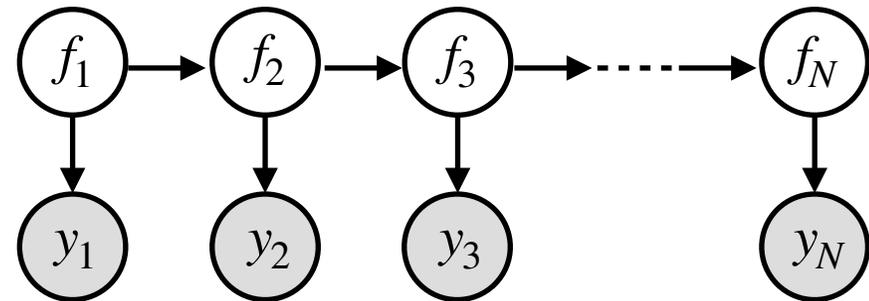
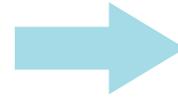


- GPs provide flexible priors for modelling data
- Can get predictions + uncertainty estimates
- However, inference cost is *cubic* in data size
- Use *state-space method* to reduce inference cost [2]

State-space reformulation (Hartikainen et. al. [2])



Gaussian Process regression



Linear state-space model

- Use **Kalman filtering** to condition on data as they arrive
- **Linear** cost in data size

Model

- We used a quasi-periodic Matérn-3/2 GP to model the latent states. The kernel is:

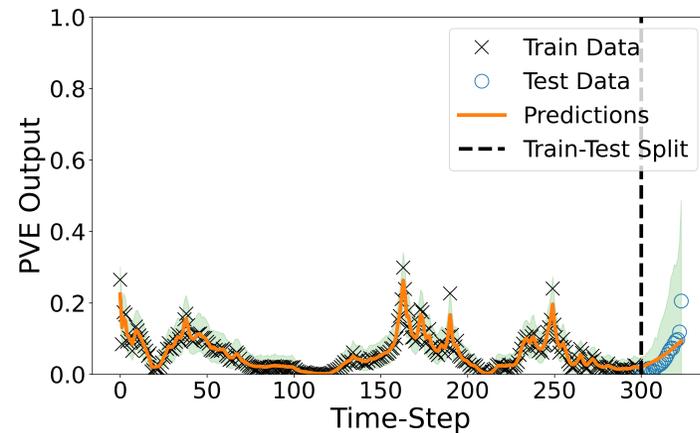
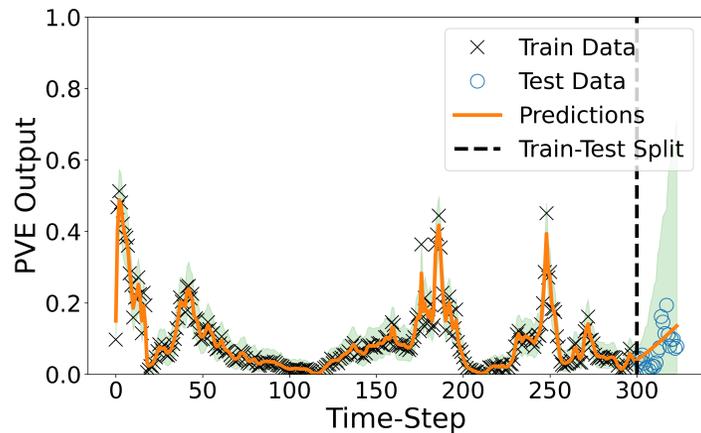
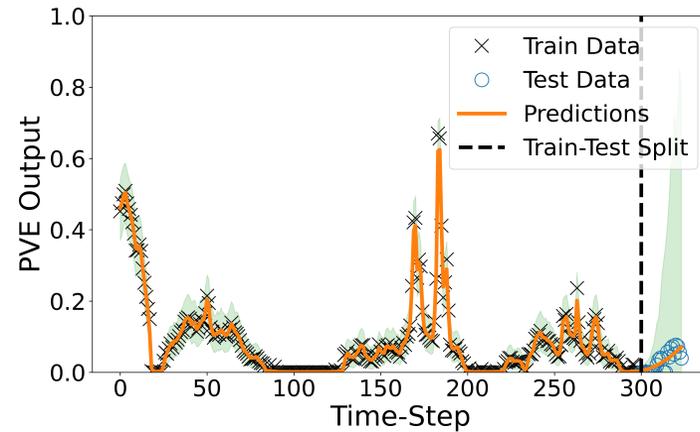
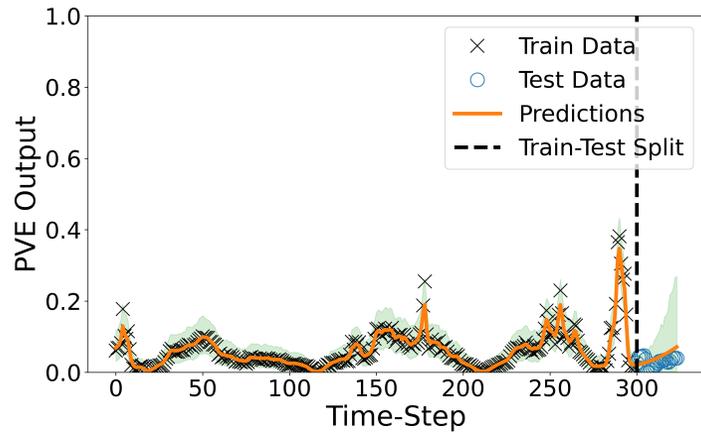
$$k(t, t') = k_{\text{matern3/2}}(t, t') + k_{\text{matern3/2}}(t, t') k_{\text{periodic}}(t, t').$$

- Use *Beta likelihood*

$$p(y | f) = \prod_{i=1}^N \mathcal{B}(y_i | \alpha(f_i), \beta(f_i)),$$

to model data in $[0, 1]$.

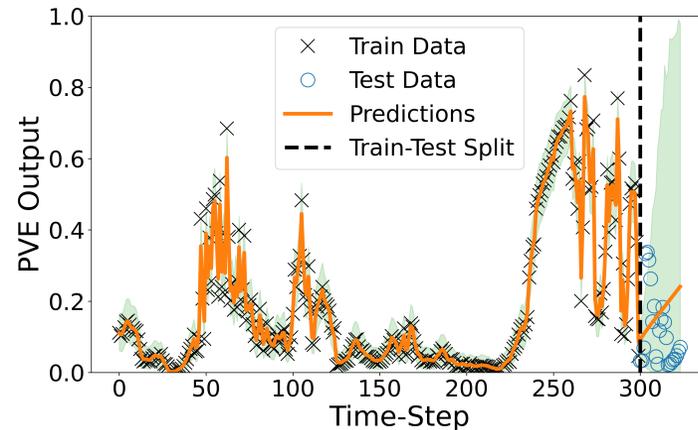
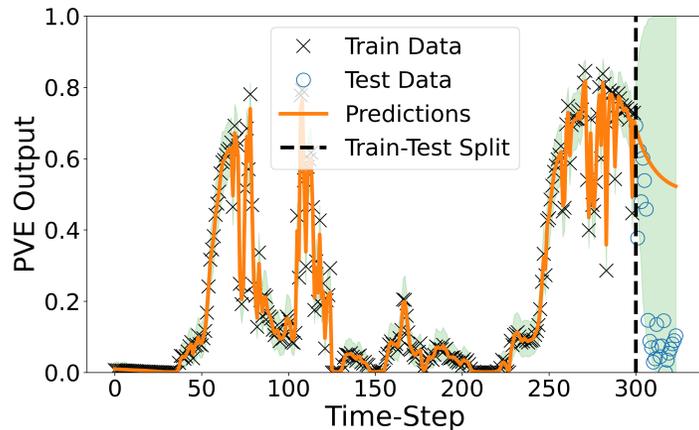
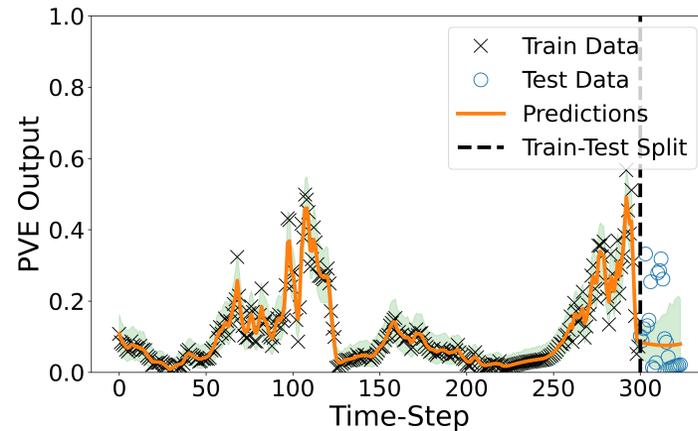
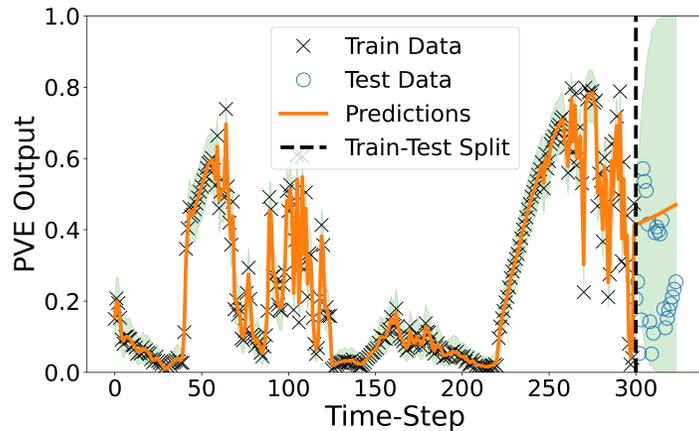
Results



- Surprisingly good predictions on a “calm” day
- **Note:** we’ve only used the past PV readings as regressors

PV predictions on date 2018-01-29 at four random locations

Results



- However, predictions are under-confident when timeseries is highly volatile
- We also considered spatio-temporal GPs to take into account spatial correlations, but achieved worse

PV predictions on date 2018-02-01 at four random locations

Results

Model	MAE ↓ (mean ± std)	NLPD ↓ (median ± m.a.d.)
Persistence	0.119 ± 0.060	N/A
Yesterday	0.152 ± 0.091	N/A
Hourly smoothing	0.125 ± 0.061	N/A
Simple exponential smoothing	0.117 ± 0.058	-11.1 ± 11.1
Seasonal exponential smoothing	0.110 ± 0.049	-12.2 ± 10.4
Vector autoregression	0.129 ± 0.071	N/A
Our model	0.109 ± 0.050	-12.9 ± 13.8

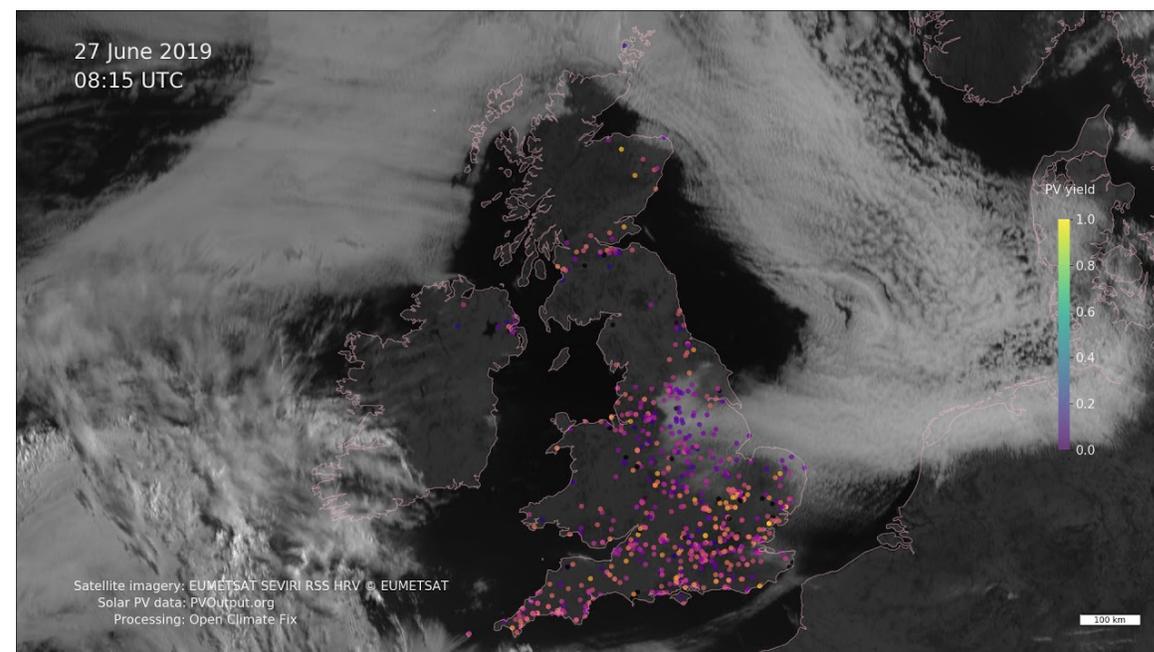
- Results are *marginally* better than several baseline models we tested on
- Metrics used: mean absolute error (MAE), negative log-predictive density (NLPD)

Summary

- Being able to predict solar power production a few hours in advance is incredibly useful for power grid planning, which may help to reduce CO2 emission and costs associated with the use of solar power
- We focussed on the use of Gaussian processes for prediction and quantifying uncertainties
- Using only the PV time series as inputs, we can get good predictions on “calm” days
- However, predictions are under-confident on “noisy” days
- At the current stage though, hard to justify its use over simpler baselines

Discussion

- **Cloud cover**, as well as other weather variables, play an important role in solar power output
⇒ Currently exploring how to incorporate this information
- We may also try to “learn” underlying latent dynamics using e.g. Latent Force Models [3] or Neural SDEs [4]



Link: <https://www.youtube.com/watch?v=IOp-tj-lJpk>

References

[1] Open Climate Fix. Nowcasting. <https://www.openclimatefix.org/projects/nowcasting/>

[2] Hartikainen, Jouni, and Simo Särkkä. "Kalman filtering and smoothing solutions to temporal Gaussian process regression models." *International workshop on machine learning for signal processing*. IEEE, 2010.

[3] Alvarez, Mauricio, David Luengo, and Neil D. Lawrence. "Latent force models." *Artificial Intelligence and Statistics*. PMLR, 2009.

[4] Li, Xuechen, et al. "Scalable gradients for stochastic differential equations." *International Conference on Artificial Intelligence and Statistics*. PMLR, 2020.