

# Deep Spatio-Temporal Forecasting of Electrical Vehicle Charging Demand

Tackling Climate Change with Machine Learning

Frederik Boe Hüttel<sup>1</sup>, Inon Peled<sup>1</sup>, Filipe Rodrigues<sup>1</sup> and Francisco C. Pereira<sup>1</sup>.

---

<sup>1</sup> Department of Management, Technical University of Denmark, Lyngby, Denmark.

# Introduction

- Electric Vehicles (EVs) offers low carbon emission solutions to reverse rising emission trends assuming the energy provided is green.
- Forecasting the Charging demand can help energy providers supplying green energy to meet the demand.
- One of the challenges in forecasting the EV charging demand is to model the complex spatial and temporal dependencies between Charging Stations.

# Spatio-Temporal Forecasting

Consider a temporal signal  $X = \{x_1, x_2, \dots, x_t\}$  and a topology  $G$  over the spatial domain.

Spatio-temporal forecasting can be viewed as learning a function  $f$  on topology  $G$  with temporal signal  $X$ .

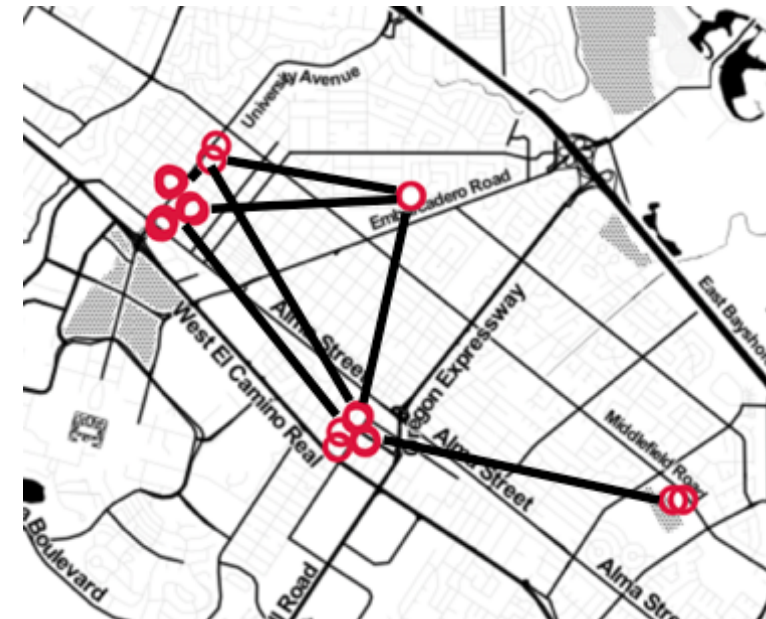
$$[X_{t+1}, \dots, X_{t+T}] = f(G; (X_{t-n}, X_{t-1}, X_t)).$$

We parameterise the function  $f$  with *Deep Learning*

# Topology

We consider multiple ways to model the topology:

1. A raster map over the spatial domain.
2. A Graph with EVCS as nodes and weighted edges with the distance between them



# Modelling

To capture the spatial features, we apply:

1. Convolutional Neural Network
2. Graph Convolution Neural Network

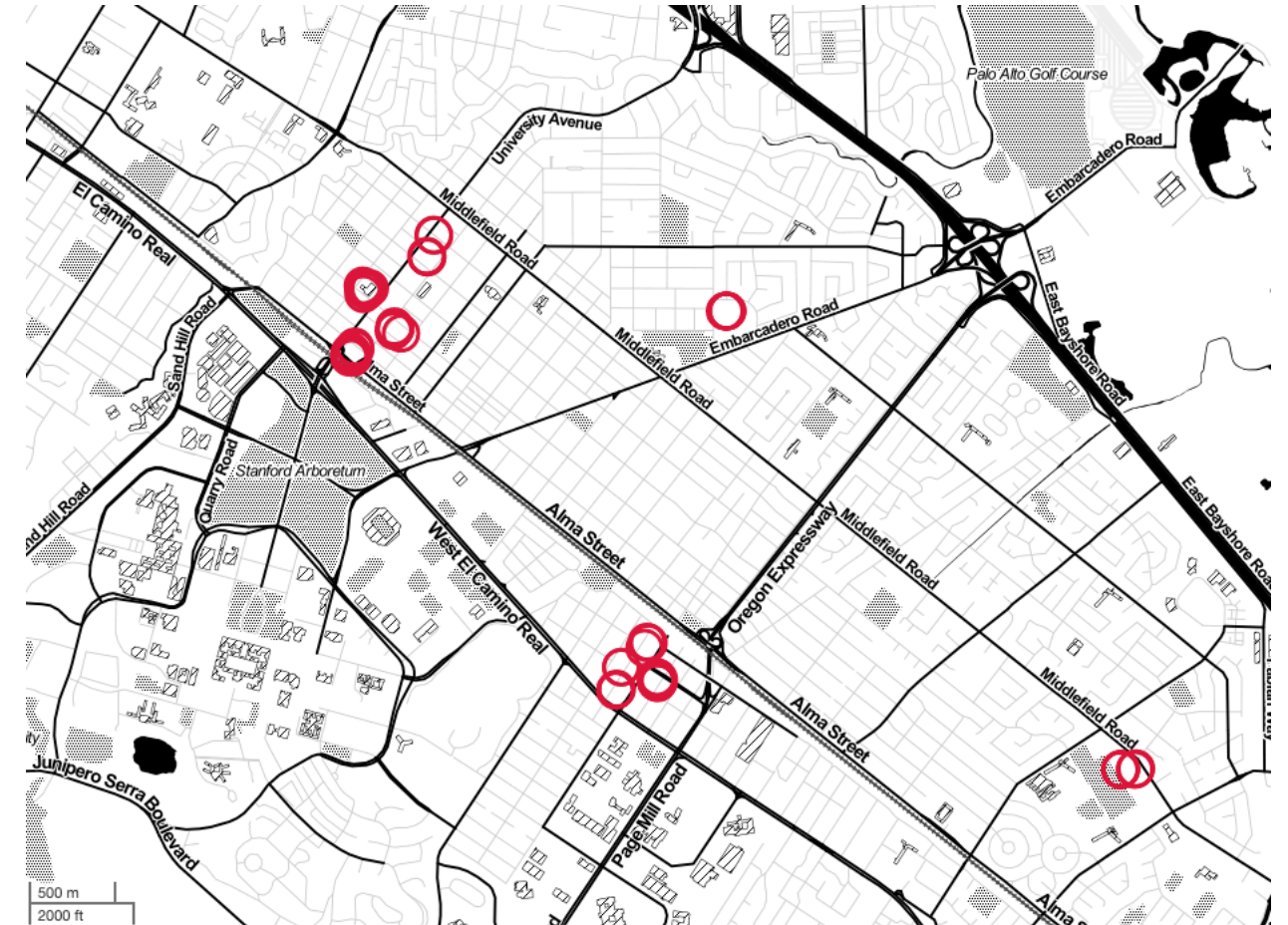
To capture temporal dynamics, we apply *Long Short-term memory* on the extracted spatial features.

We denote the forecasted value as  $\widehat{X}_{t+1:t+T}$  and the realised value as  $X_{t+1:t+T}$  and train the model under *mean absolute error*:

$$\mathcal{L} = |X_{t+1:t+T} - \widehat{X}_{t+1:t+T}| + \lambda\beta^2.$$

# Data

- The data consists of public EV charging transactional from Palo Alto<sup>5</sup>.
- Contains energy consumed for each charging session.
- We focus on using energy consumption (kWh) for a transaction.
- The consumption is aggregated into a daily energy demand for each of the stations in Palo Alto.



---

<sup>5</sup> Data available at [Link](#)

# Experimental results

We test the propose models for 3 different forecast horizons<sup>6</sup>:

Model	1 Day	7 Days	30 Days
AR(30)	178	251	252
VAR(30)	189	203	201
CNN	144	243	211
CNN + LSTM	95	192	187
<b>T-GCN</b>	<b>61</b>	<b>184</b>	<b>161</b>

---

<sup>6</sup> Code available at: [Github](#).

# Conclusion

- We have argued for the use of publicly available data for forecasting the electric vehicle charging demand.
- Based on the experimental results, Graph Convolutional Networks have superior forecasting performance compared to other methods.
- We hope that the results and arguments encourage researchers to use publicly available data for research into EV charging demand.

