

# Toward efficient calibration of higher-resolution ESMs

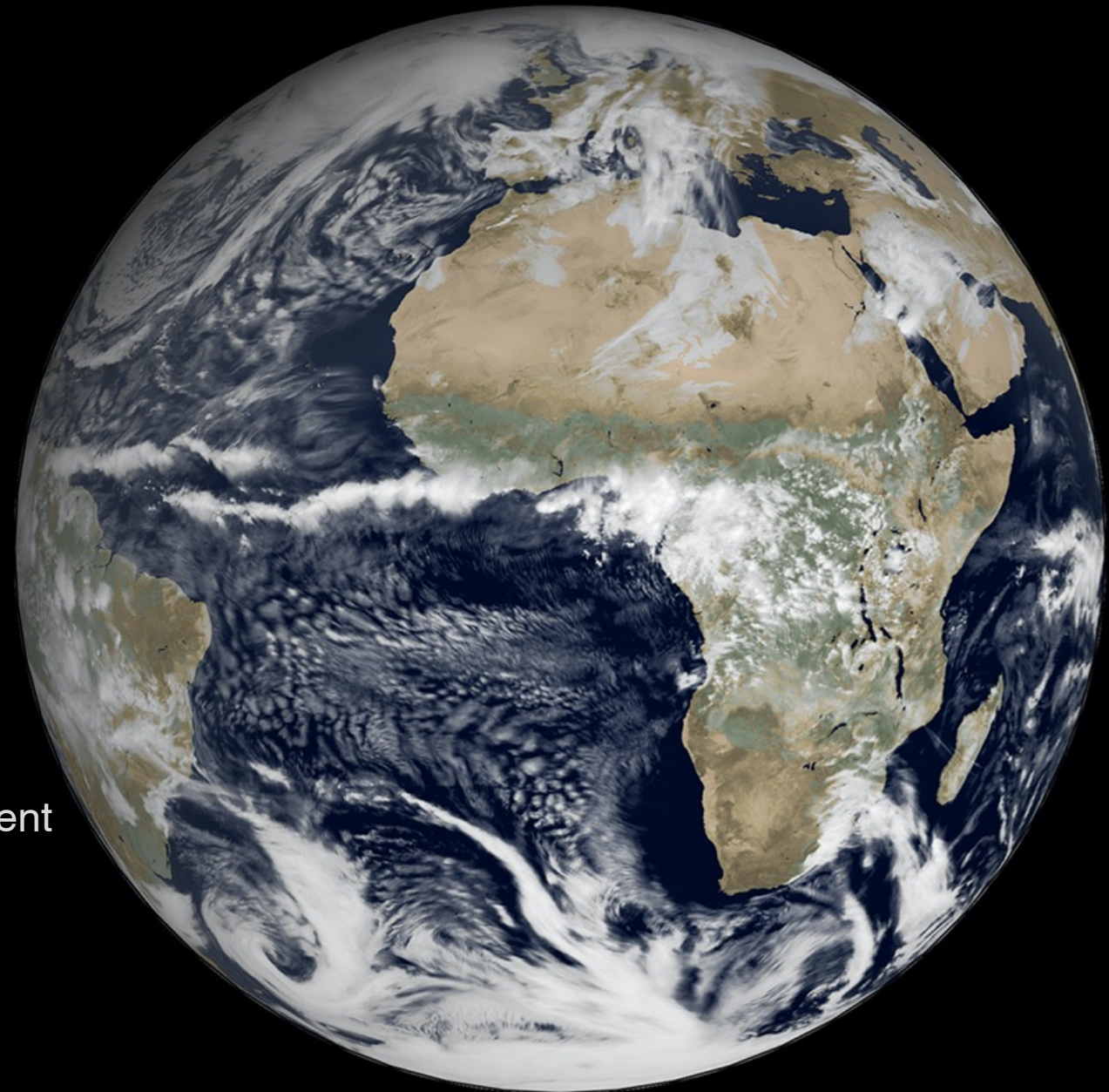
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1.4 km resolution global simulation from Wedi et al., *JAMES*, (2020)

# Introduction

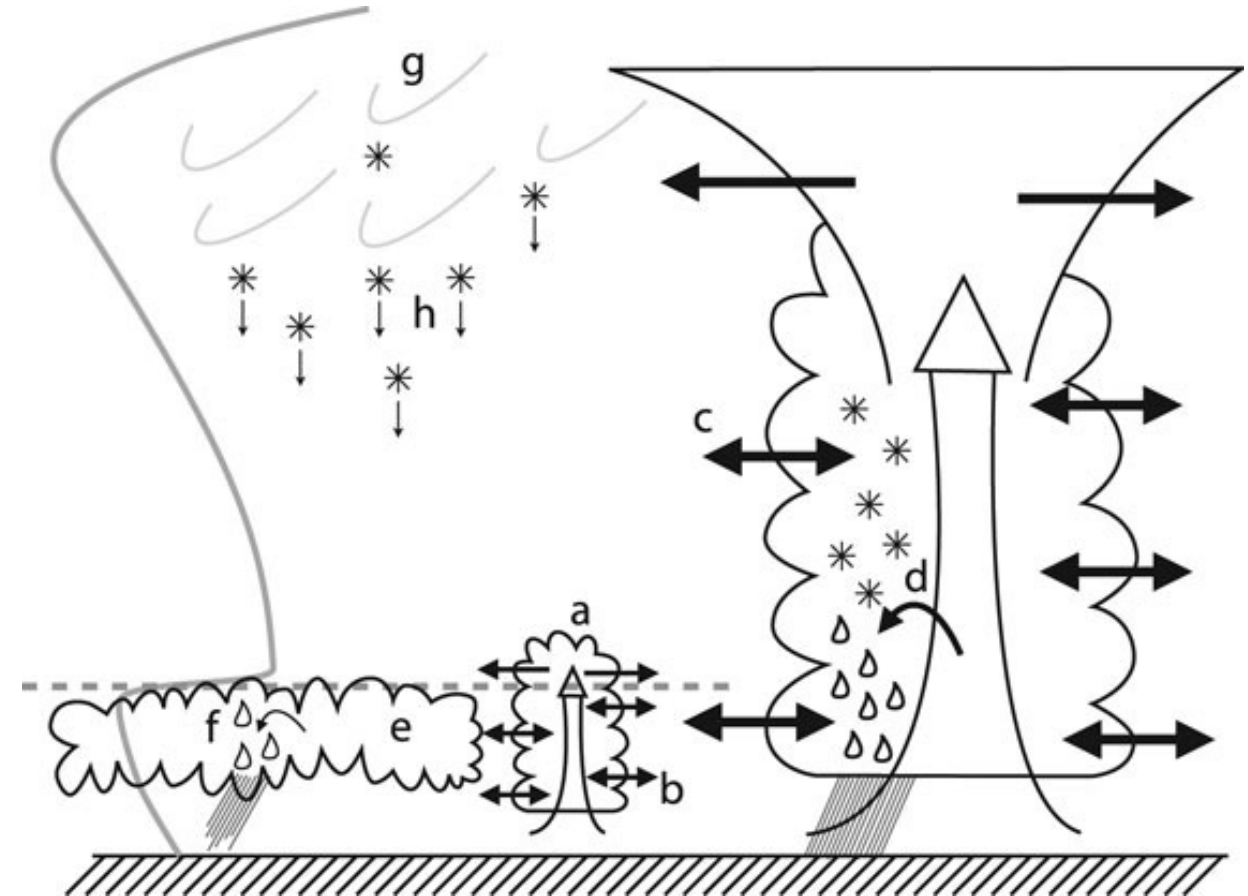
- High-resolution ( $<10$  km) simulations with ESMs are required to support adaptation planning and decision-making, especially for hydrologic change.
- CMIP6-class ESMs have spatial resolution  $\sim 100$  km, so **downscaling** is required.
- Tuning/calibration is a major barrier to development of higher-resolution ESMs.
- Here we present a proof-of-concept study showing that a convolutional neural network can be used to reduce CPU time for ESM calibration.



# Model calibration (aka Tuning)



- Unresolved (sub-grid scale) processes involve poorly constrained parameters
- Esp. clouds, precipitation, radiation.



Mauritsen et al., JAMES, (2012)

# CLIMATE MODEL SIMULATIONS



# CESM SIMULATIONS

- CESM1.0.4 F-compset: CAM4 physics, 1850 SSTs and sea ice.
- Run identical 100-member PPEs at f09, f19 and f45 resolutions
- Each realization is run for 36 months
- Analyze annual climatologies
- Upscale f19 and f45 outputs to f09 grid (192 x 288)

Methods		Results		Conclusions
Parameter	Description (CAM4 parameter name)	Min	Default	Max
$x_1$	Fraction of hygroscopic SO <sub>4</sub>	0.0	0.0	1.0
$x_2$	Spatial uniformity of BC (1 = globally uniform)	0.0	0.0	1.0
$x_3$	Scaling factor for global BC mass	0.0	1.0	40.0
$x_4$	Altitude for insertion of uniform BC layer	0.0	–	39.0
$x_5$	RH threshold for low cloud formation (cldfrc_rhminl)	0.80	0.88	0.99
$x_6$	Effective radius of liquid cloud droplets over ocean (cldopt_rliqocean)	8.4	14.0	19.6
$x_7$	Timescale for consumption rate of shallow CAPE (hkconv_cmftau)	900	1800	14 440
$x_8$	RH threshold for high cloud formation (cldfrc_rhminh)	0.50	0.50	0.85
$x_9$	Timescale for consumption rate of deep CAPE (zmconv_tau)	1800	3600	28 800

Covey et al. (2013); Fletcher et al., *ACP*, (2018)



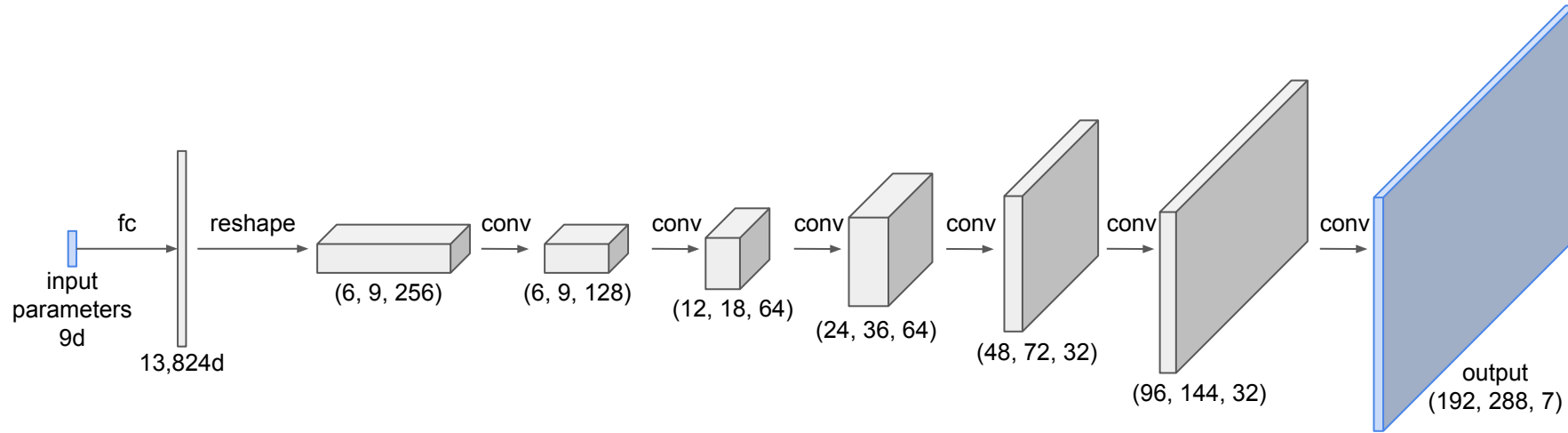
# CNN ARCHITECTURE

# CNN ARCHITECTURE

Methods

Results

Conclusions



- Input: 9d vector of parameter values projected to 13,824d then 6 x 9 x 256.
- Series of transpose convolutions (+ batch normalization and leaky rectified linear unit)
- Output is array of predictions 192 x 288 x 7, where 7 is number of variables.
- CNN implemented in TensorFlow 2.2 using Keras API.

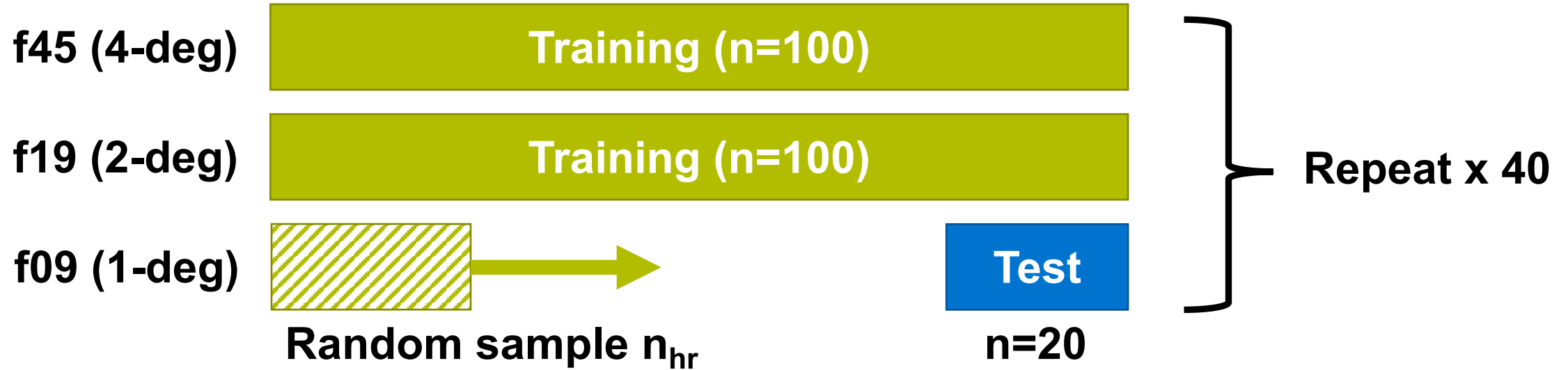


# LOW-TO-HIGH RES EMULATOR

Methods

Results

Conclusions



- Inspired by Anderson and Lucas (2018): Train CNN on lower-resolution (f45 and f19) cases, plus an increasing number ( $n_{hr}$ ) of f09 cases.
- Quantify SS for predicting n=20 unseen high-res cases at different values of  $n_{hr}$
- Compare to a baseline prediction: annual climatological mean difference





# RESULTS

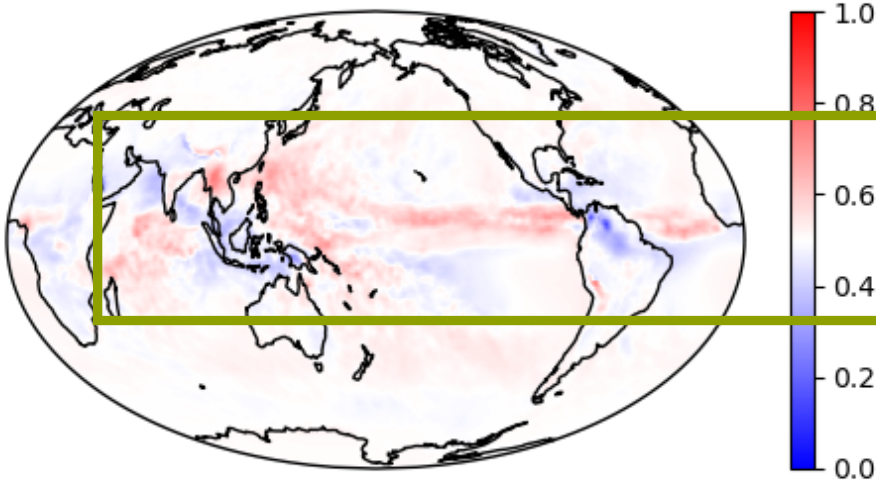
# HIGH-RES PREDICTION EXAMPLE

Methods

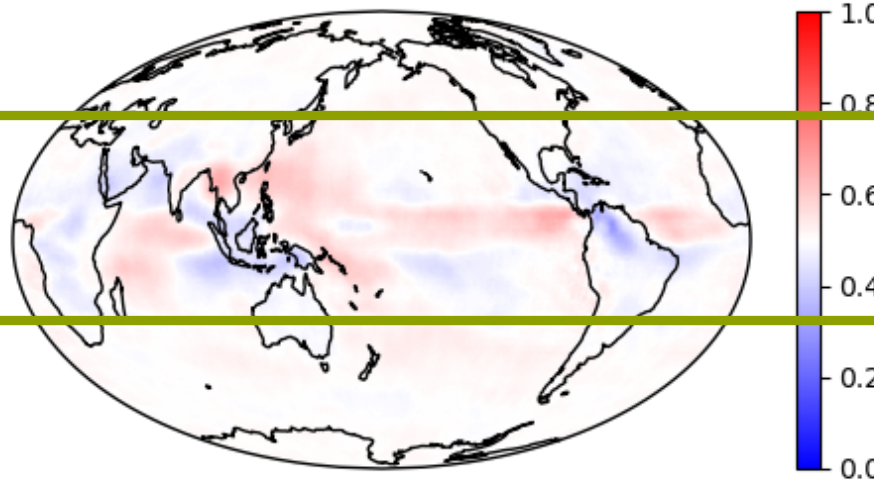
Results

Conclusions

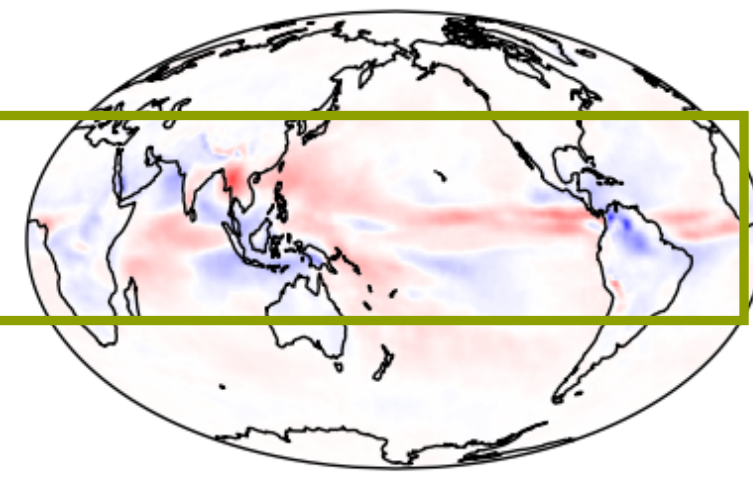
CAM4 (1-deg)



CNN ( $L_{MSE}$ )



CNN ( $L_{SS}$ )



Realization 2 of 20

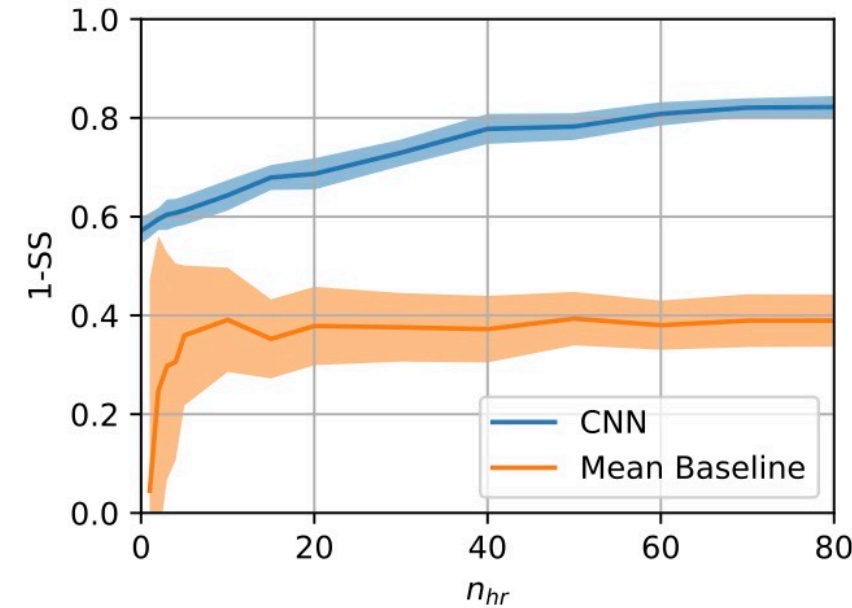
- Averaged over all realizations, cross-validated SS = 0.82 (0.73 for precipitation)
- Skill is ~25% higher using  $L_{SS}$  than  $L_{MSE}$ .

# LOW-TO-HIGH RES EMULATOR

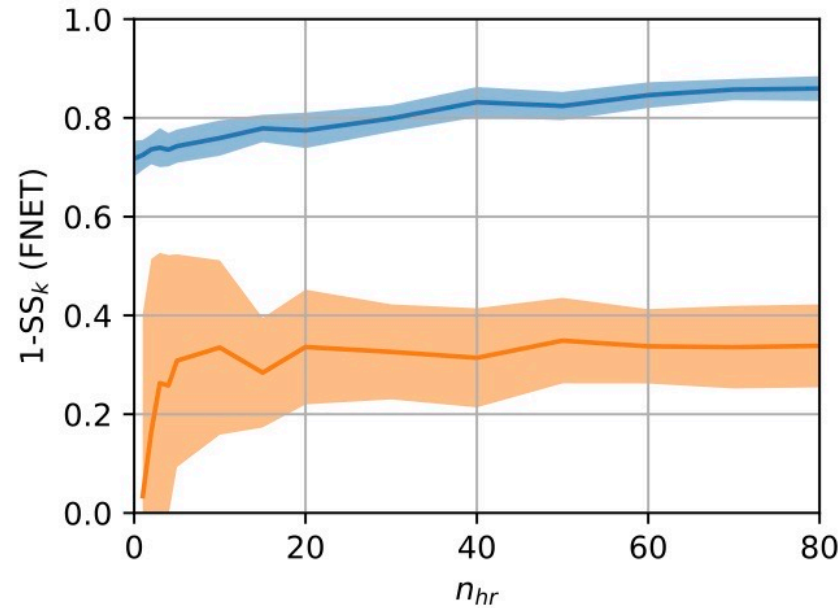
Methods

Results

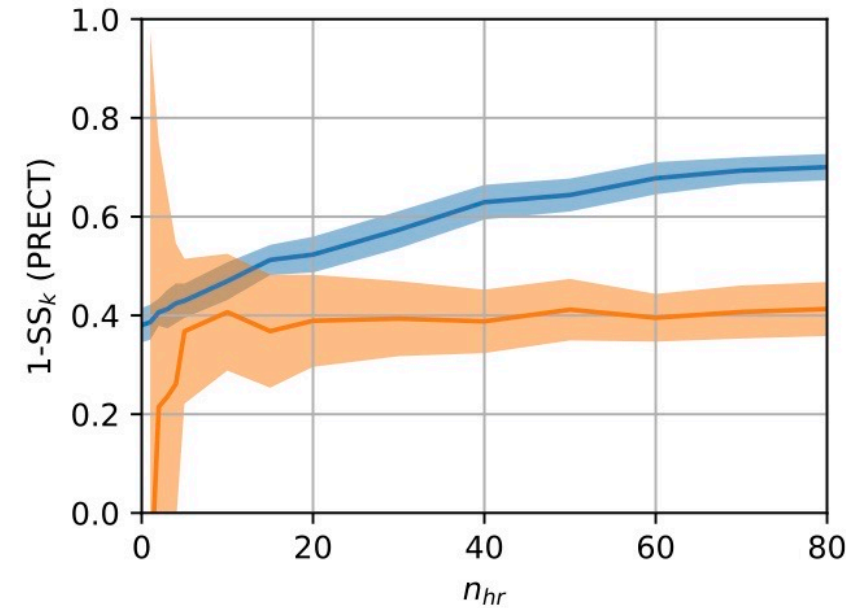
Conclusions



(a) Mean



(b) FNET



(c) PRECT

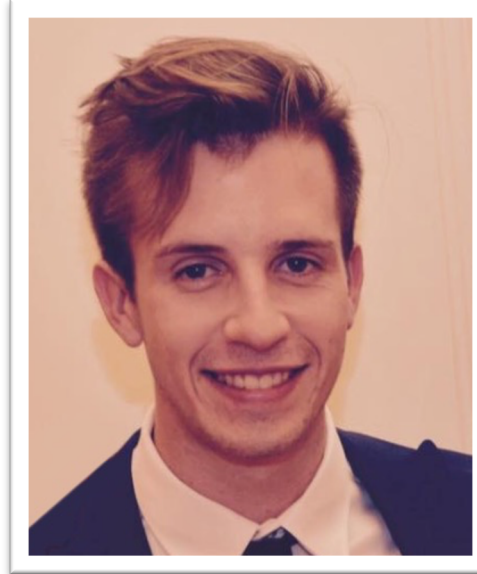
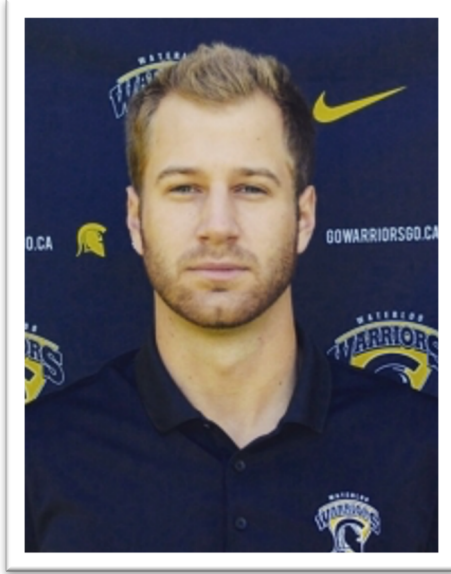
- Mean SS  $\sim 0.6$  with **only** low-res cases; increases to 0.8 including high-res cases.
- Skill plateaus at  $n_{hr} \sim 40$ : limited benefit from running more high-res cases.
- CNN skill exceeds baseline when  $n_{hr} > 10$ , even for precipitation.



# Conclusions

- We present a ML-based method that could support calibration of high-resolution ESMs.
- The CNN accurately predicts the spatially-resolved impacts of nine tuning parameters on atmospheric outputs in CAM4, even for precipitation.
- Using the CNN reduces required CPU time by 20-40%. Potential extensions to seasonal, regional outputs, high-resolution, and time-evolving simulations.
- Operational settings require simultaneous calibration of multiple components, fully-coupled integrations (not just atmosphere).





# Thank you!

C. G. Fletcher, W. McNally, J. G. Virgin: *Toward efficient calibration of higher-resolution ESMs* (in prep)

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# EXTRA SLIDES



# CNN TRAINING/VALIDATION

Methods

Results

Conclusions

f09 (1-deg)

Training

Random sample n=80

Test

n=20

- Train CNN to predict differences due to parameters: perturbed – default.
- Normalize predictors (**x**) and target difference maps (**Y**)
- Train on two different loss functions:  $L_{MSE}$  and  $L_{SS}$  (SS from Pierce et al. 2009)
- Quantify accuracy of predictions using *MSE* and *SS* metrics between CESM simulation and predictions by CNN



# HIGH-RES EMULATION EXAMPLE

Methods

Results

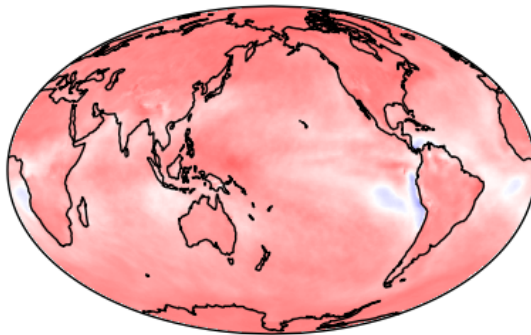
Conclusions

CAM4 (1-deg)

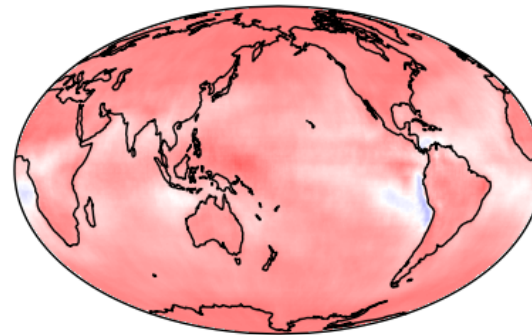
CNN ( $L_{MSE}$ )

CNN ( $L_{SS}$ )

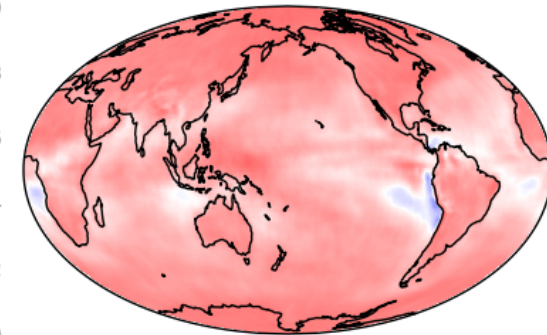
RESTOM



(a) FNET

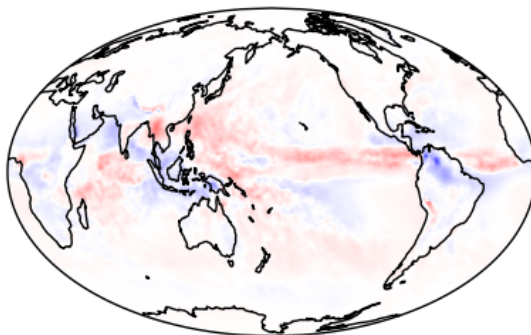


(b)  $MSE_k: 2.32e-4, 1-SS_k: 0.931$

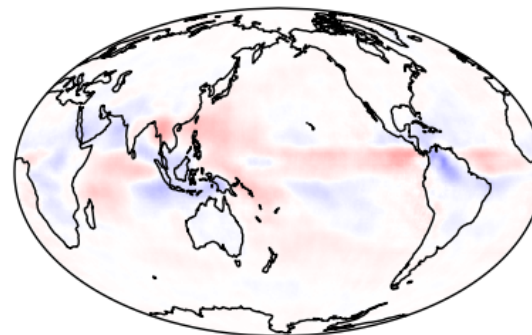


(c)  $MSE_k: 2.20e-4, 1-SS_k: 0.949$

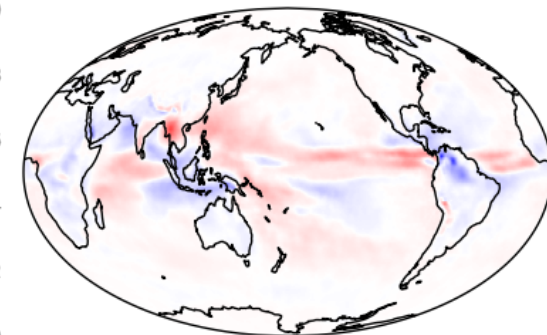
PRECT



(d) PRECT



(e)  $MSE_k: 2.28e-4, 1-SS_k: 0.610$



(f)  $MSE_k: 1.91e-4, 1-SS_k: 0.816$

Realization 2 of 20

